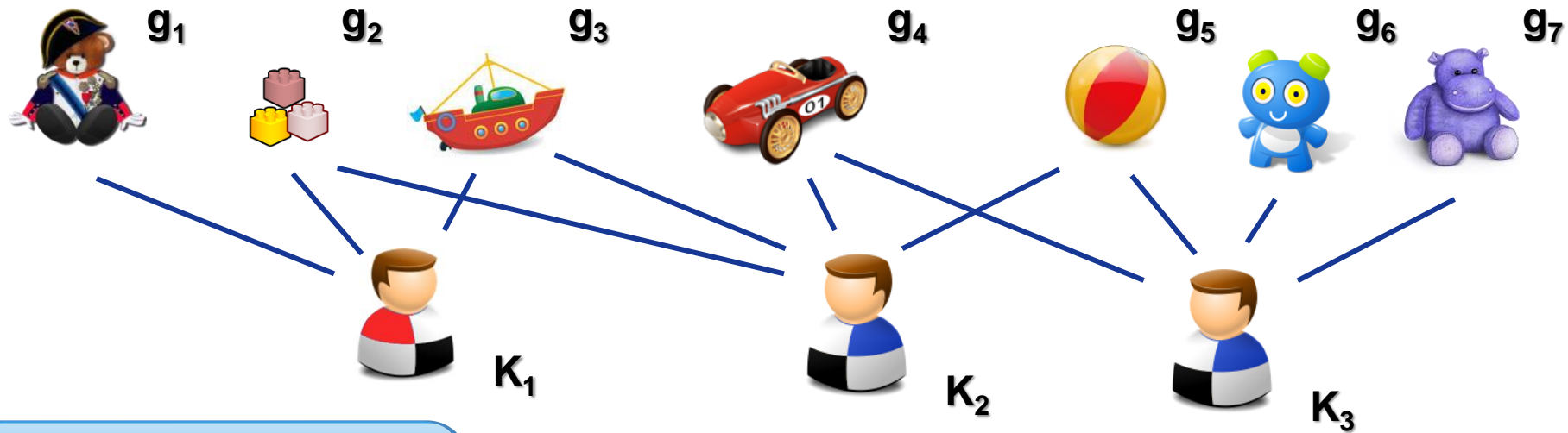


Constraint Satisfaction and Fair Multi-Objective Optimization Problems: Foundations, Complexity, and Islands of Tractability

Gianluigi Greco and Francesco Scarcello

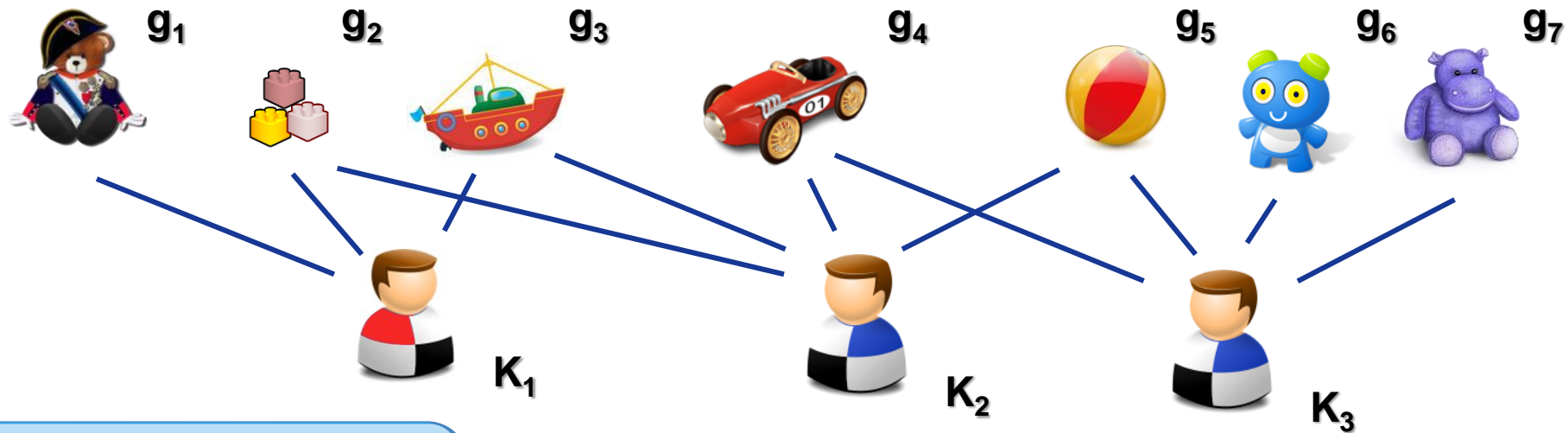


Constraint Satisfaction Problems



- Distribute the goods/presents to the kids
- Goods are indivisible

Constraint Satisfaction Problems



- Distribute the goods/presents to the kids
- Goods are indivisible

Variables

- $K_1, K_2,$ and K_3

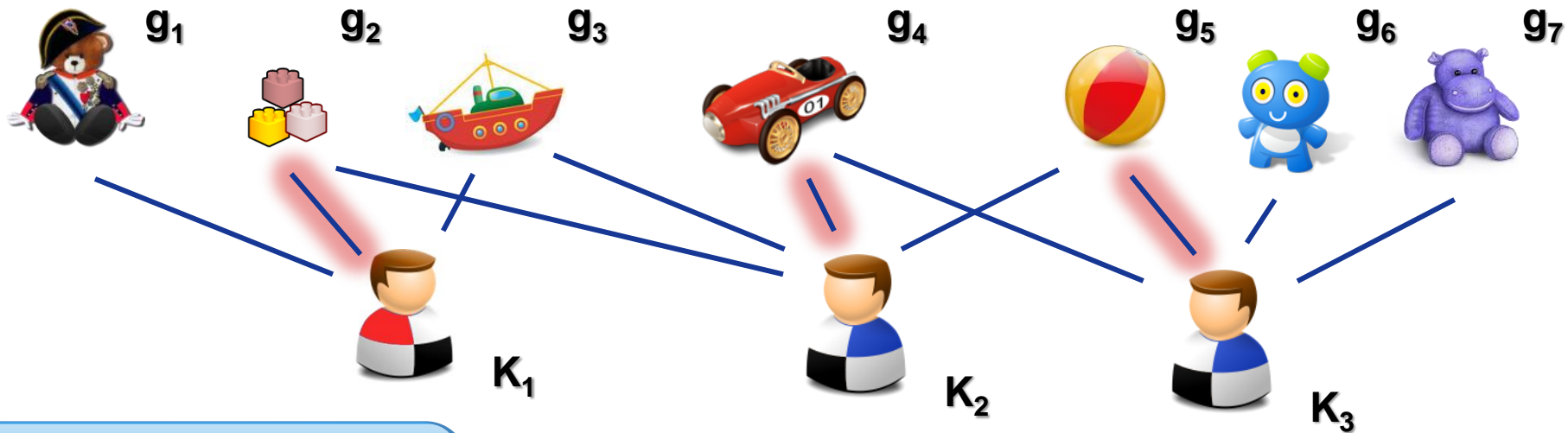
Domain

- g_1, g_2, \dots, g_7

Constraints

- $K_1 \in \{g_1, g_2, g_3\}$
- $K_2 \in \{g_2, g_3, g_4, g_5\}$
- $K_3 \in \{g_4, g_5, g_6, g_7\}$
- $K_1 \neq K_2, K_2 \neq K_3$

Constraint Satisfaction Problems



- Distribute the goods/presents to the kids
- Goods are indivisible

■ Solution

- $K_1 \rightarrow g_2$
- $K_2 \rightarrow g_4$
- $K_3 \rightarrow g_6$

■ Variables

- $K_1, K_2, \text{ and } K_3$

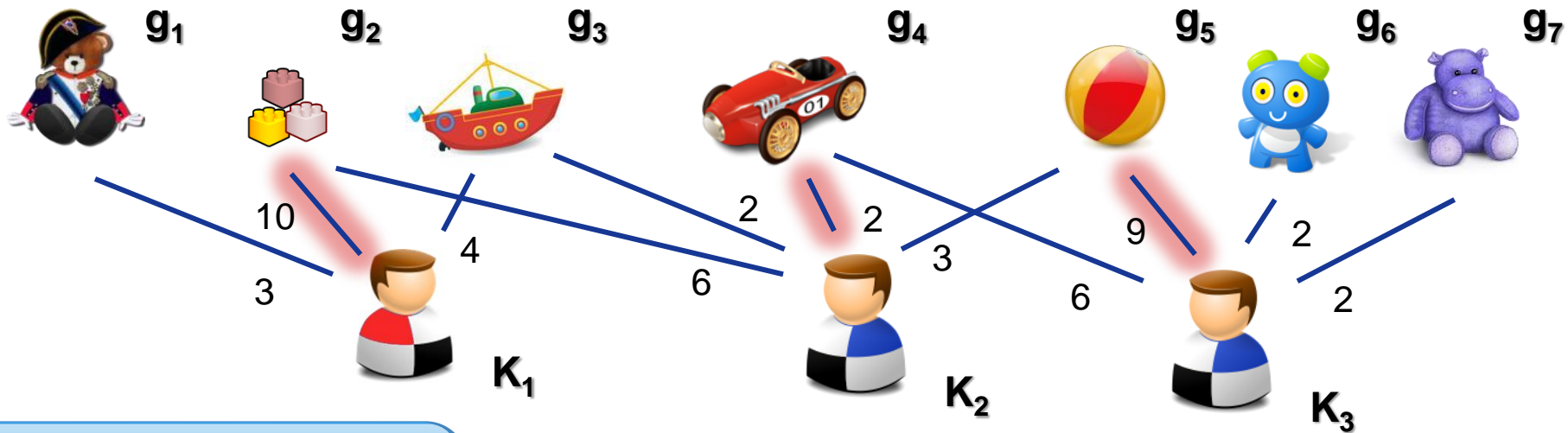
■ Domain

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Optimization Functions in CSPs



- Distribute the goods/presents to the kids
- Goods are indivisible

- Kids have preferences over the presents

- **Valuation Function:** $\mathcal{F} = \langle w, + \rangle$

- $w(K_1/g_1) = 3$
- $w(K_1/g_2) = 10$
- ...

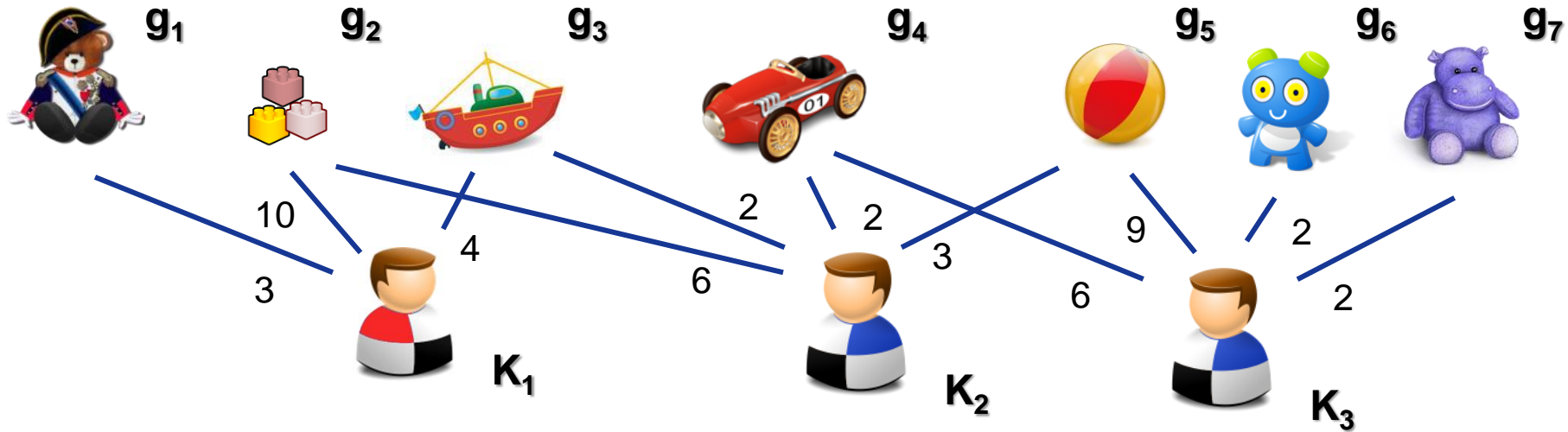
- **Value of the Solution**

- $w(K_1/g_1) + w(K_2/g_4) + w(K_3/g_6) = 21$

- **Optimal (MAX) Solution**

- Maximizes the *social welfare*

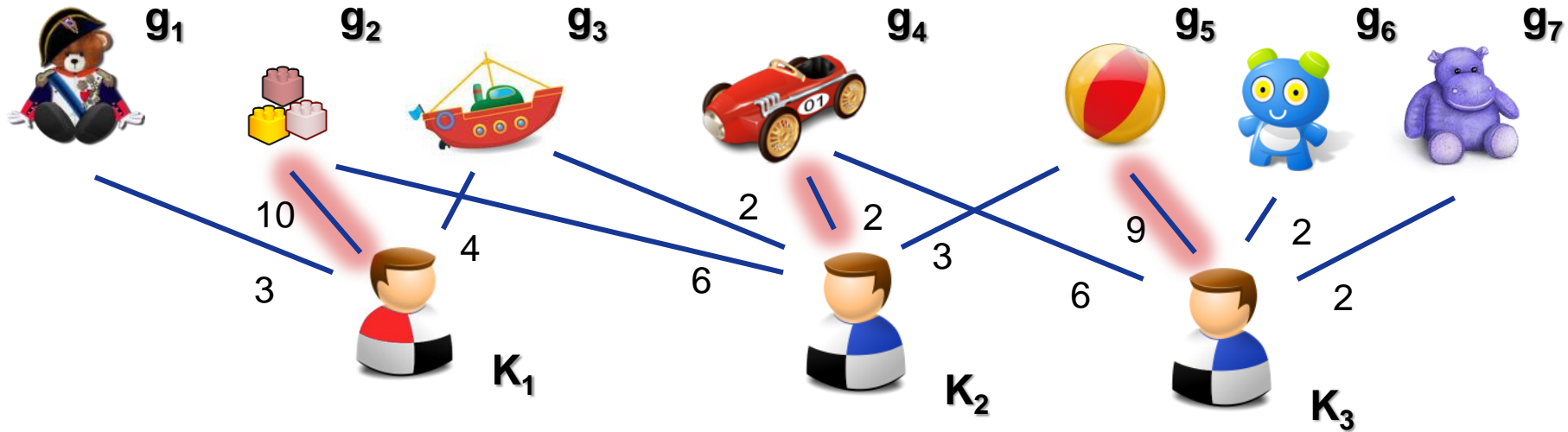
Multi-Objective Optimization



- **Different Valuations:** $\{\mathcal{F}_1, \mathcal{F}_2, \mathcal{F}_3\}$
 - \mathcal{F}_h is defined on K_h
- **Combination Strategies:**

Four vertical dashed lines for writing notes.

Multi-Objective Optimization



■ **Different Valuations:** $\{\mathcal{F}_1, \mathcal{F}_2, \mathcal{F}_3\}$

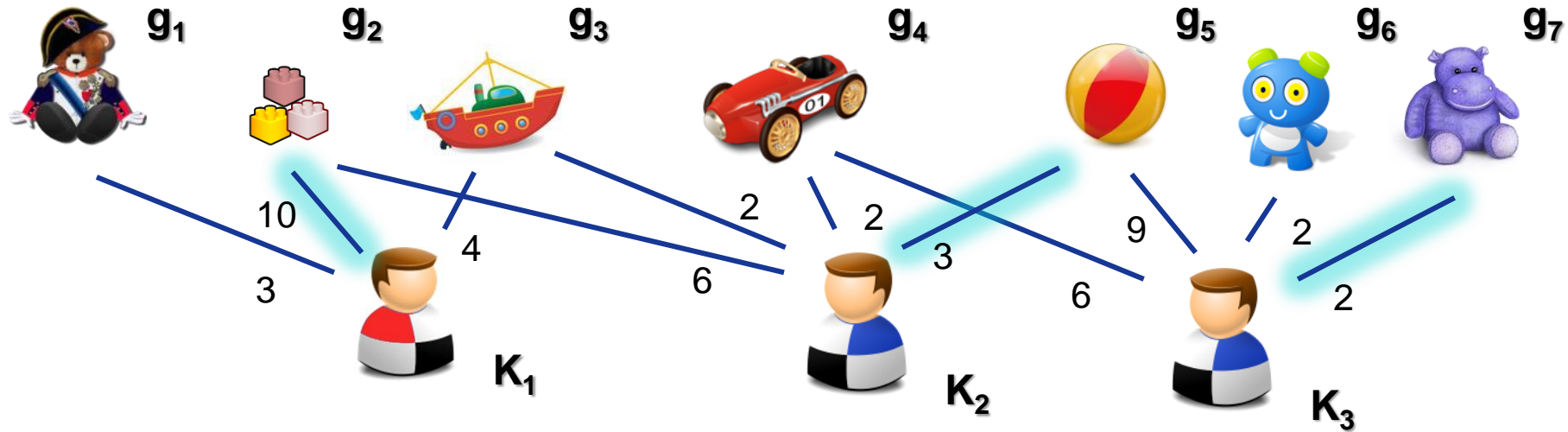
□ \mathcal{F}_h is defined on K_h

■ **Combination Strategies:**

□ MAX-SUM (*social welfare*)

10	2	9

Multi-Objective Optimization



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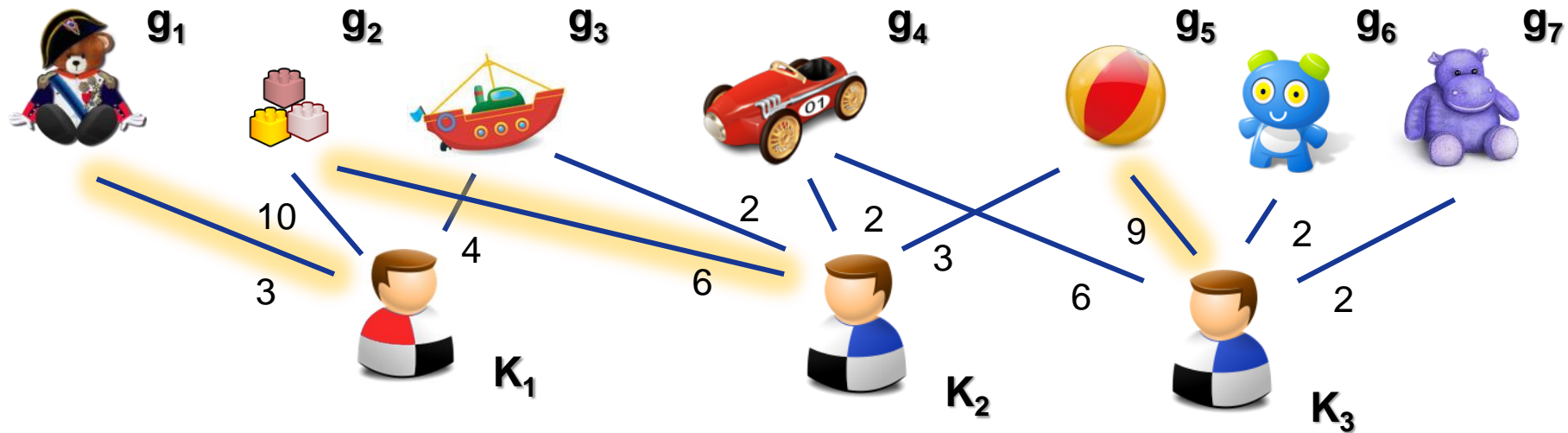
- Combination Strategies:**

- MAX-SUM (*social welfare*)

- LEX

10	2	9
10	3	2

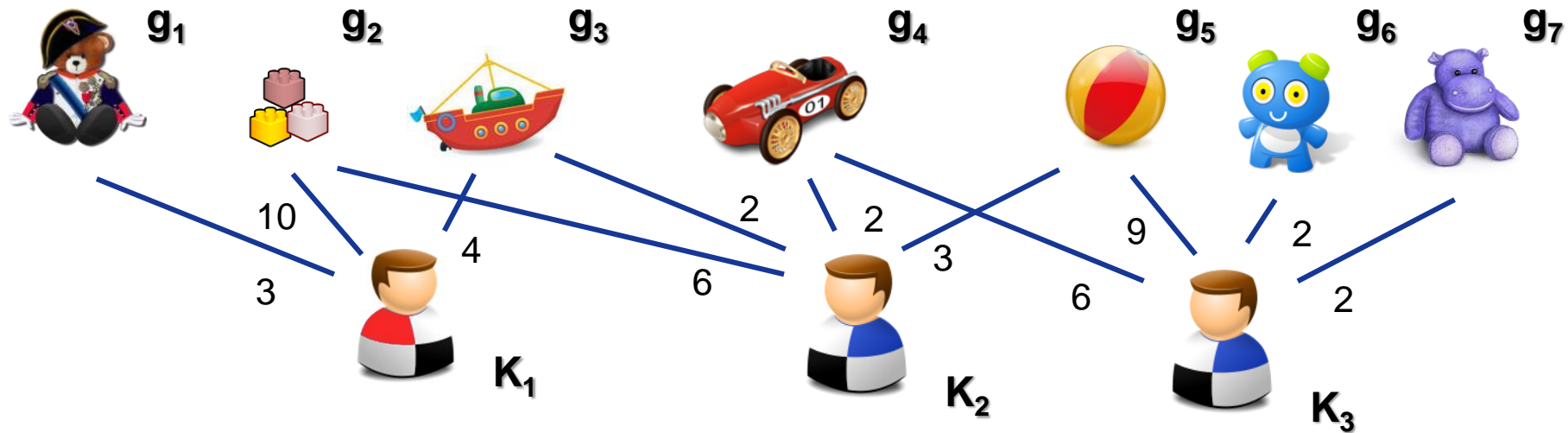
Multi-Objective Optimization



- Different Valuations:** $\{\mathcal{F}_1, \mathcal{F}_2, \mathcal{F}_3\}$
 - \mathcal{F}_h is defined on K_h
- Combination Strategies:**

MAX-SUM (<i>social welfare</i>)	10	2	9
LEX	10	3	2
PARETO	e.g. 3	e.g. 6	e.g. 9

Related Literature



- **Different Valuations:** $\{\mathcal{F}_1, \mathcal{F}_2, \mathcal{F}_3\}$
 - \mathcal{F}_h is defined on K_h
- **Combination Strategies:**

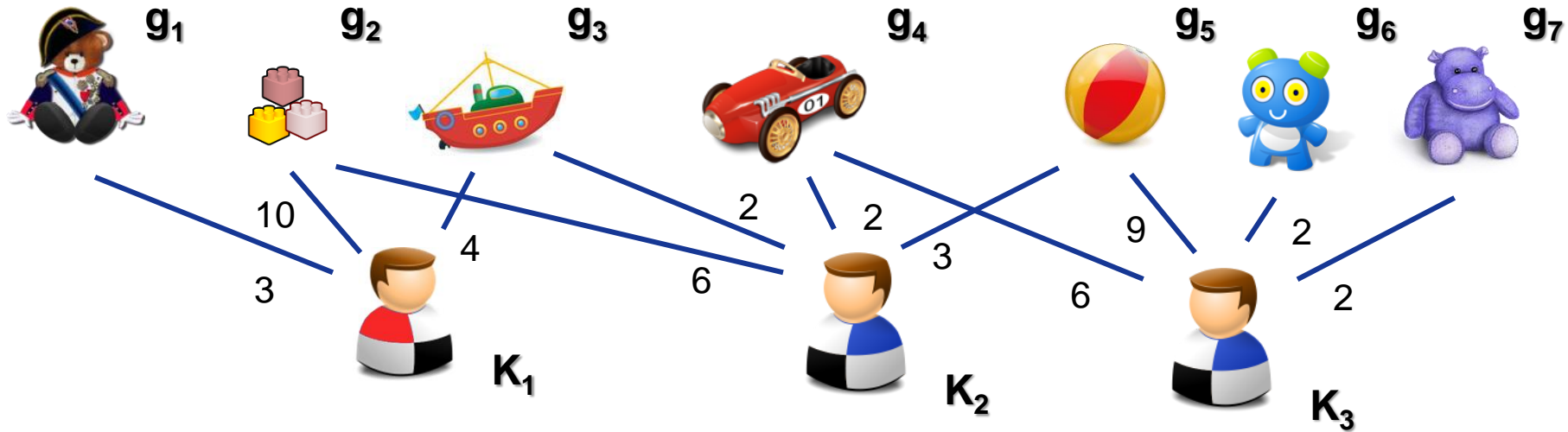
□ MAX-SUM (<i>social welfare</i>)	10	2	9
□ LEX	10	3	2
□ PARETO e.g.	3	6	9

→ [Bistarelli *et al.*, Rossi *et al.*]

→ [Freuder *et al.*]

→ [Torrens and Faltings]

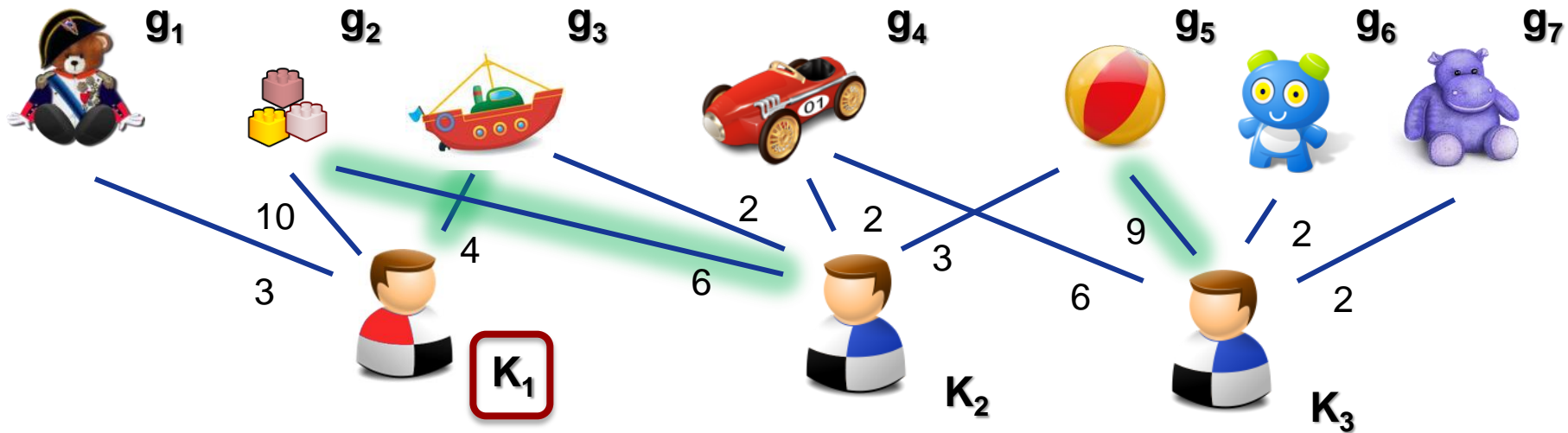
Related Literature



The Santa Claus Problem:

Santa's goal is to distribute presents in a way that the least lucky kid is as happy as possible.

Related Literature

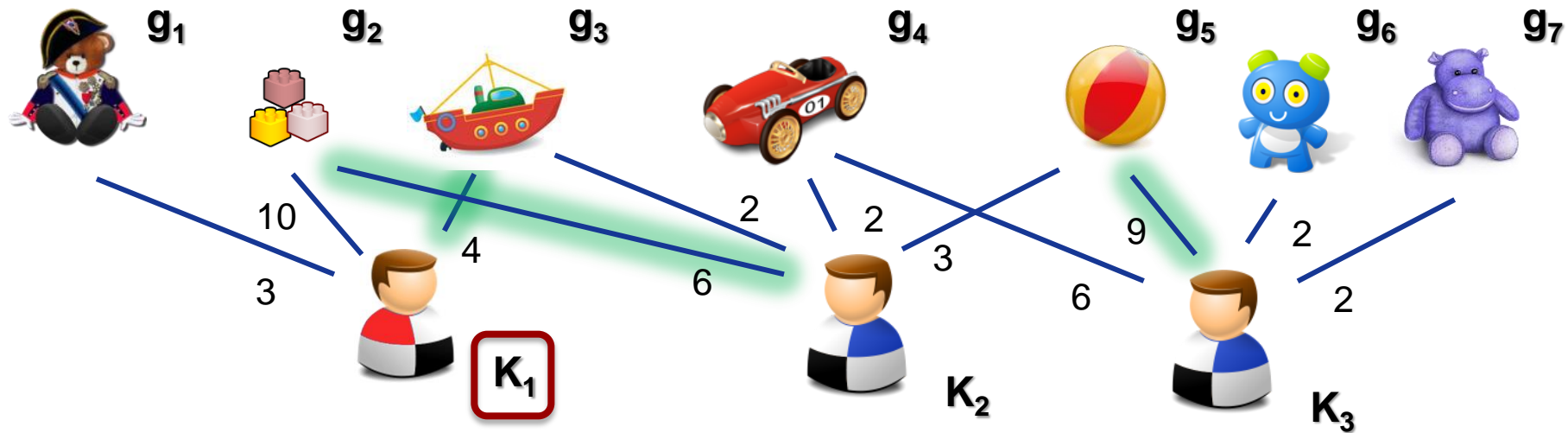


The Santa Claus Problem:

Social welfare = 19 (max 21)

Santa's goal is to distribute presents in a way that the least lucky kid is as happy as possible.

Related Literature



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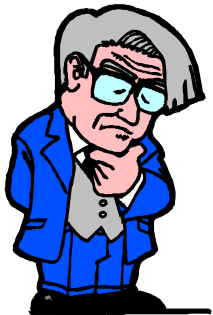
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FAIR OPTIMIZATION

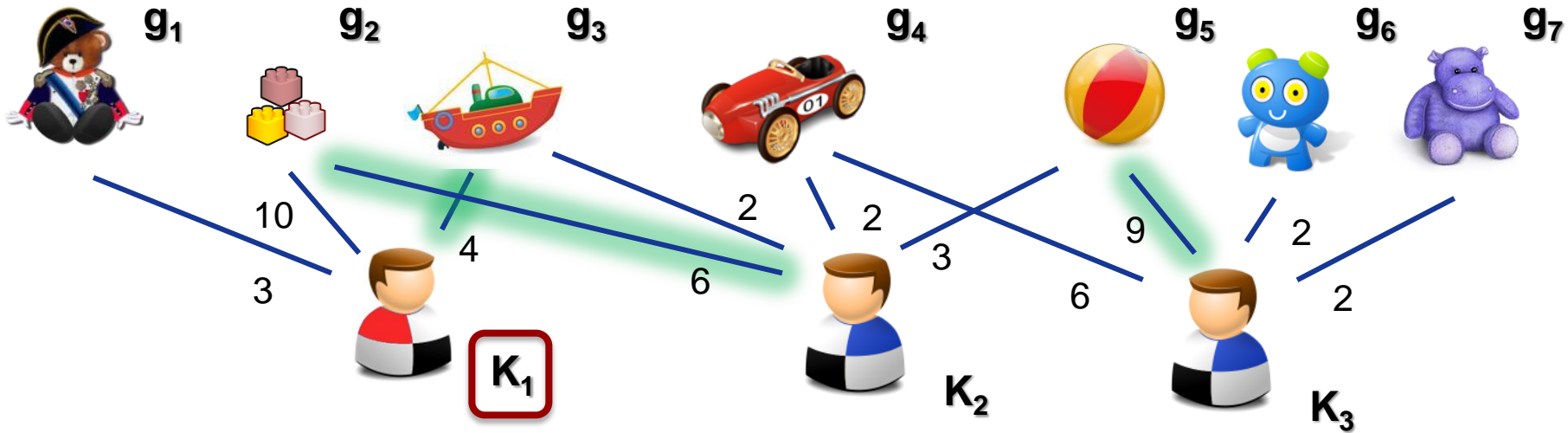
□ MAX-MIN



[Snow and Freuder, Dubois and Fortemps, Bouveret and Lematre]



Related Literature



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FAIR OPTIMIZATION

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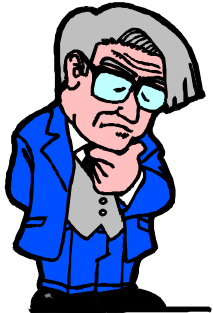
Limited expressiveness

• functions on one variable/constraint

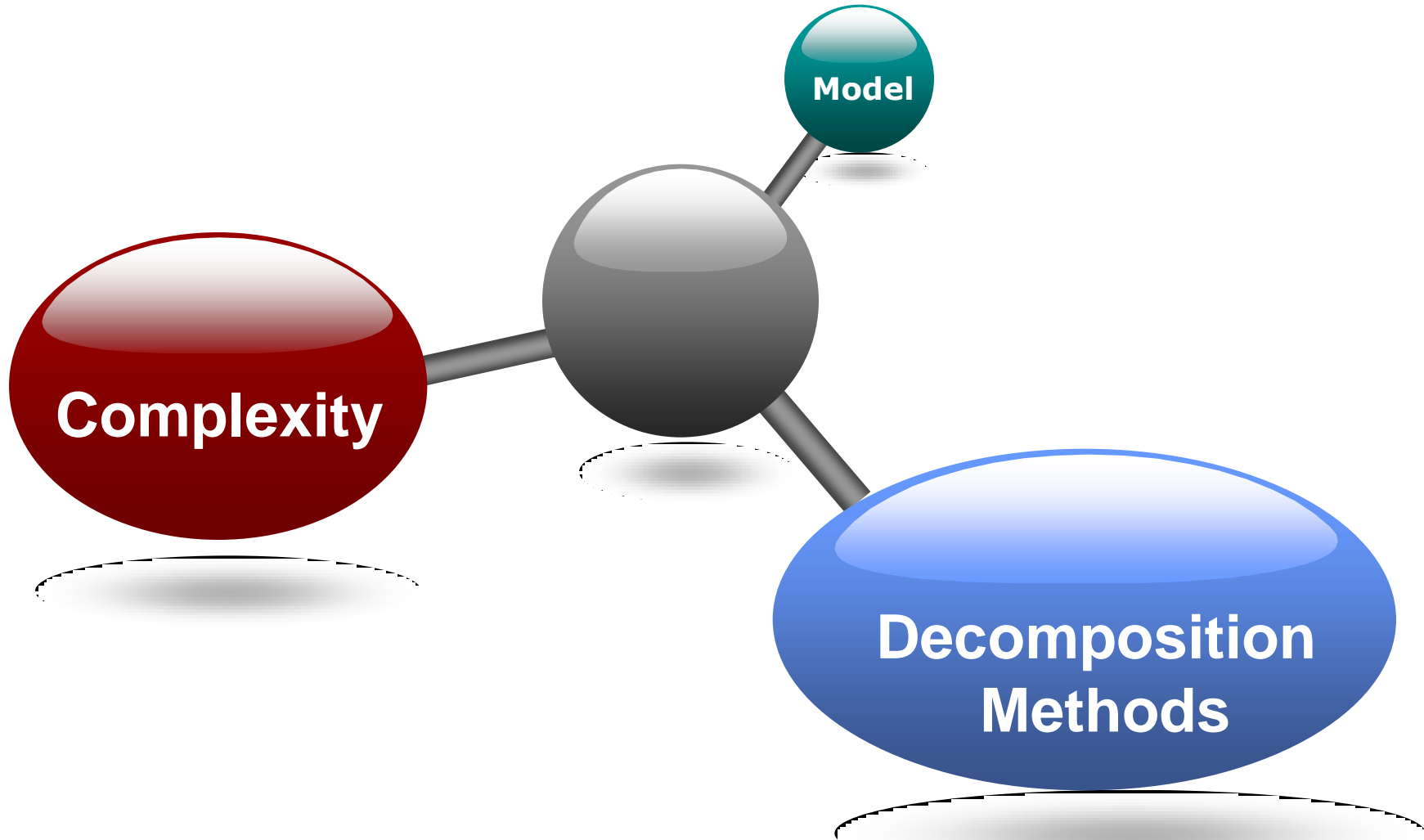


No complexity analysis

[Snow and Freuder, Dubois and Fortemps, Bouveret and Lematre]



Overview



The Model

- $L = \{\mathcal{F}_1, \dots, \mathcal{F}_n\}$ is a set of valuation functions
- $\mathcal{F}_i = \langle w_i, \oplus_i \rangle$ is such that
 - $w_i : \bar{X}_i \times \mathcal{U} \mapsto \mathbb{R}$, with $\bar{X}_i \subseteq \text{Var}$
 - \oplus_i is a *commutative, associative, and closed* binary operator
- $\mathcal{F}_i(\theta) = \bigoplus_{\{X/u \in \theta \mid X \in \bar{X}_i\}} w_i(X, u)$.

$$\max_{\theta} \min_{\mathcal{F} \in L} \mathcal{F}(\theta)$$

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The Santa Claus Problem:

(possible solutions)

$\{\mathcal{F}_1, \mathcal{F}_2, \mathcal{F}_3\}$

10	2	9
10	3	2
3	6	9
4	6	6
4	6	9
⋮	⋮	⋮

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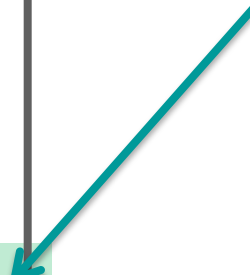
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(possible solutions)

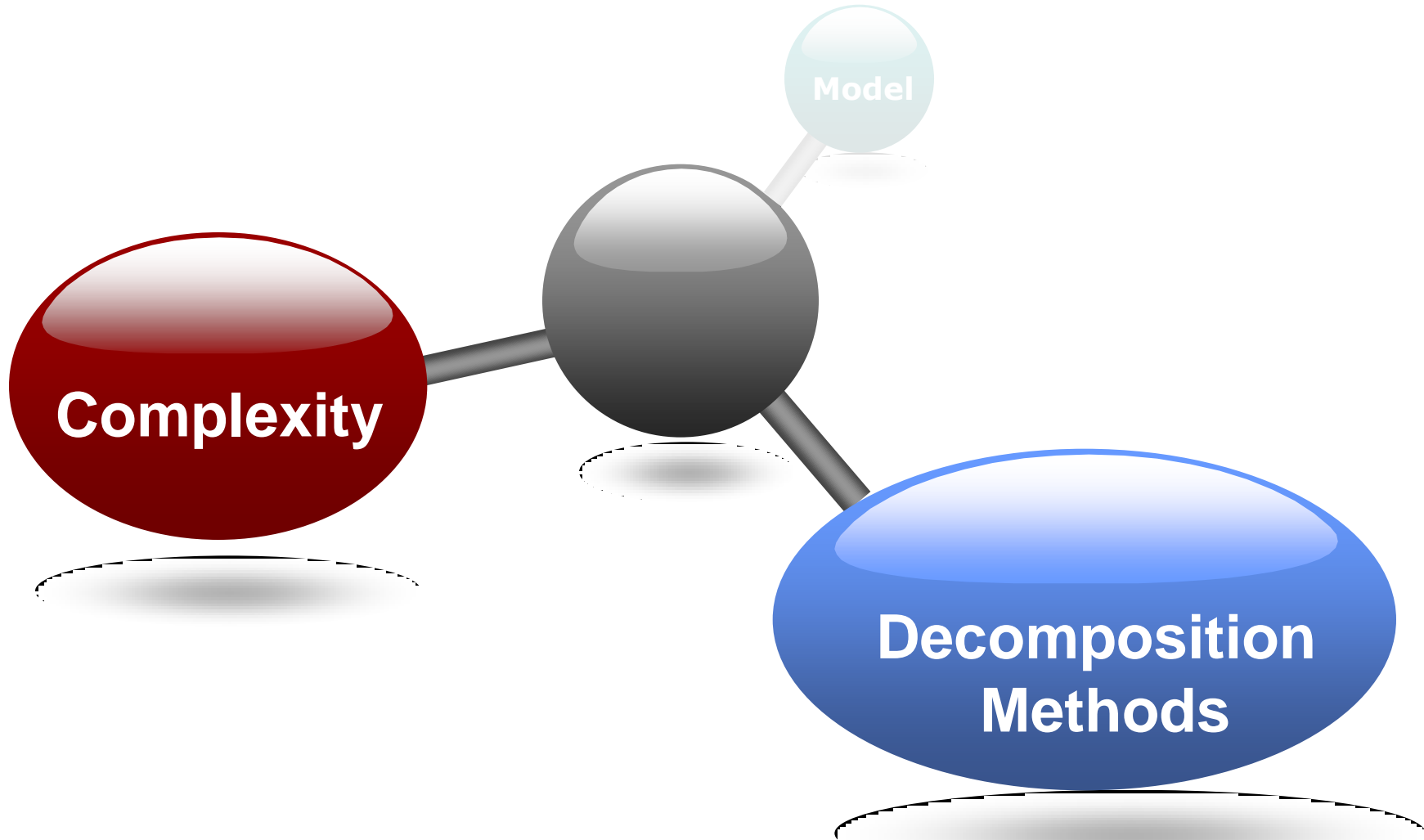
$\{\mathcal{F}_1, \mathcal{F}_2, \mathcal{F}_3\}$

10	2	9
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$$\max_{\theta} \min_{\mathcal{F} \in L} \mathcal{F}(\theta)$$

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Overview



Complexity of (LEX)MAX-MIN Solutions

- **Constraint satisfaction is NP-hard**
 - Even without optimization functions...
- **Tractable classes of CSPs**
 - Based on the values in the constraint relations
 - Based on the structure of the constraint scopes

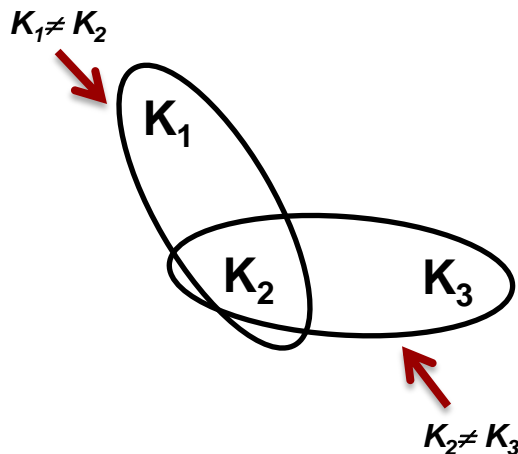
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 - Treewidth [Dechter & Pearl]

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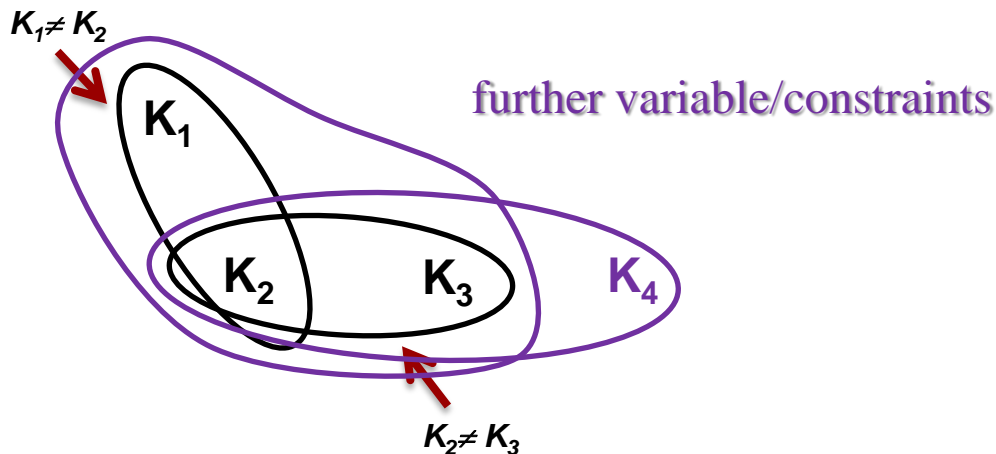
■ **CONSTRAINT HYPERGRAPH**



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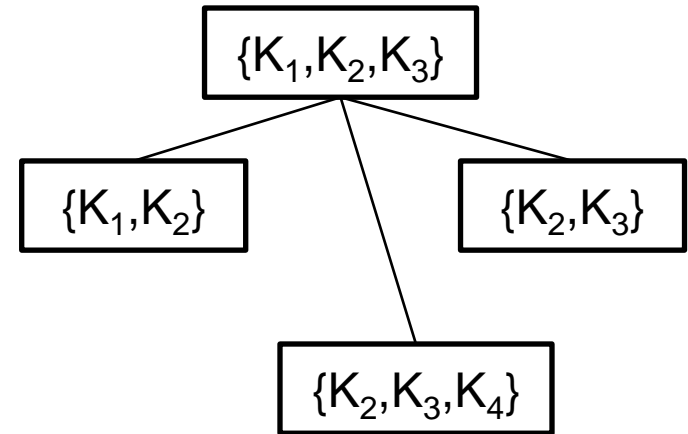
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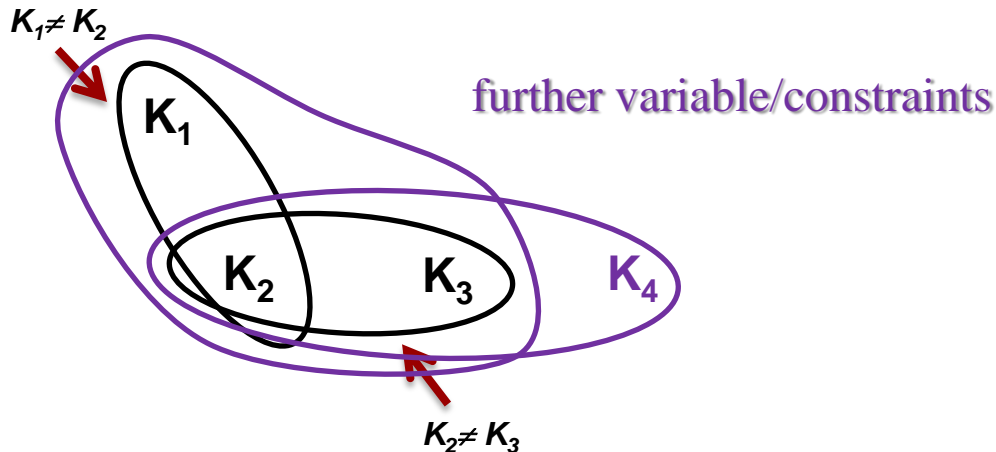
Complexity of (LEX)MAX-MIN Solutions

■ JOIN TREE

- Vertices correspond to the hyperedges
- Each variable induces a connected subtree



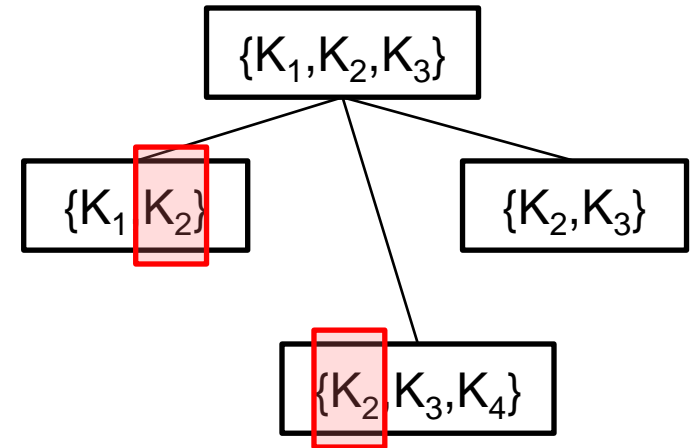
■ CONSTRAINT HYPERGRAPH



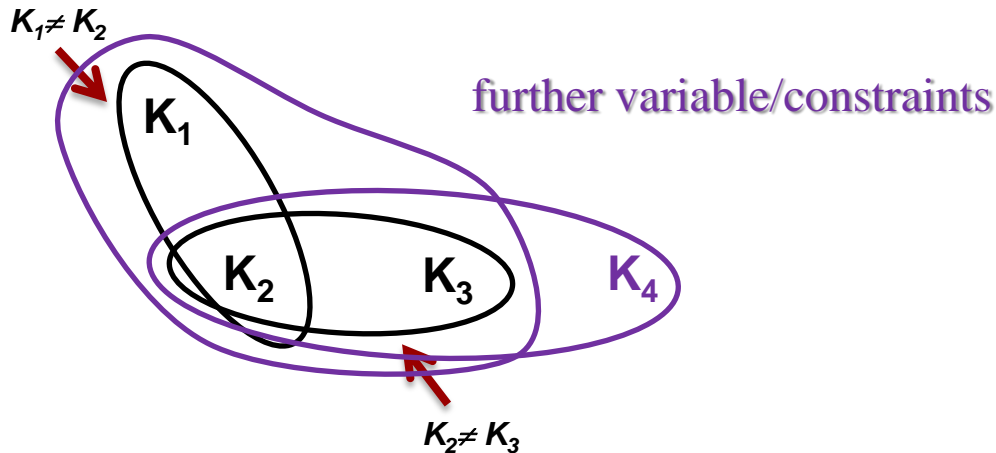
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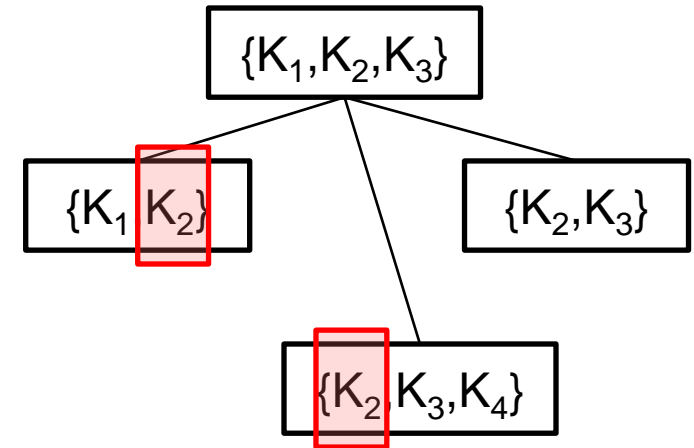
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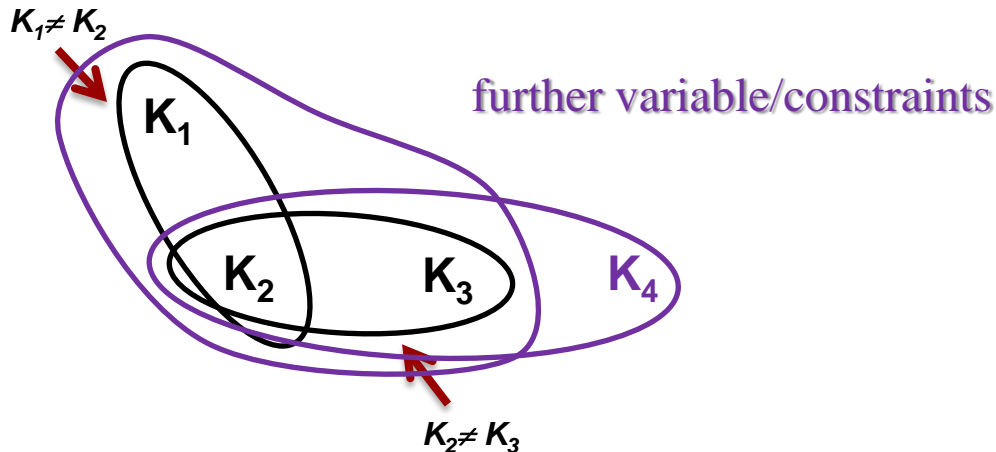
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ACYCLIC CSP

CONSTRAINT HYPERGRAPH



Complexity of Acyclic Instances

$[D, F]$	1	h	∞
1			
k			
∞			

- **Restrictions on $L = \{\mathcal{F}_1, \dots, \mathcal{F}_n\}$**
 - $\max_{\mathcal{F} \in L} |\text{dom}(\mathcal{F})| \leq D$
 - $|L| \leq F$

Complexity of Acyclic Instances

$[D, F]$	1	h	∞
1			
k			
∞	in P		



[Gottlob et al.]

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Complexity of Acyclic Instances

Dynamic programming

$[D, F]$	1	h	∞
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Dynamic programming

$[D, F]$	1	h	∞
1	in P	in P	in P
k	in P		
∞	in P	weakly NP-hard	

[Gottlob *et al.*]

- Reduction from «Partition»
- Pseudo-polynomial

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Complexity of Acyclic Instances

Dynamic programming

Reduction from «Set Packing»

$[D, F]$	1	h	∞
1	in P	in P	in P
k	in P		NP-hard
∞	in P	weakly NP-hard	

[Gottlob *et al.*]

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Complexity of Acyclic Instances

Dynamic programming

Reduction from «Set Packing»

$[D, F]$	1	h	∞
1	in P	in P	in P
k	in P		NP-hard
∞	in P	weakly NP-hard	NP-hard

[Gottlob *et al.*]

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Complexity of Acyclic Instances

Dynamic programming

Reduction from «Set Packing»

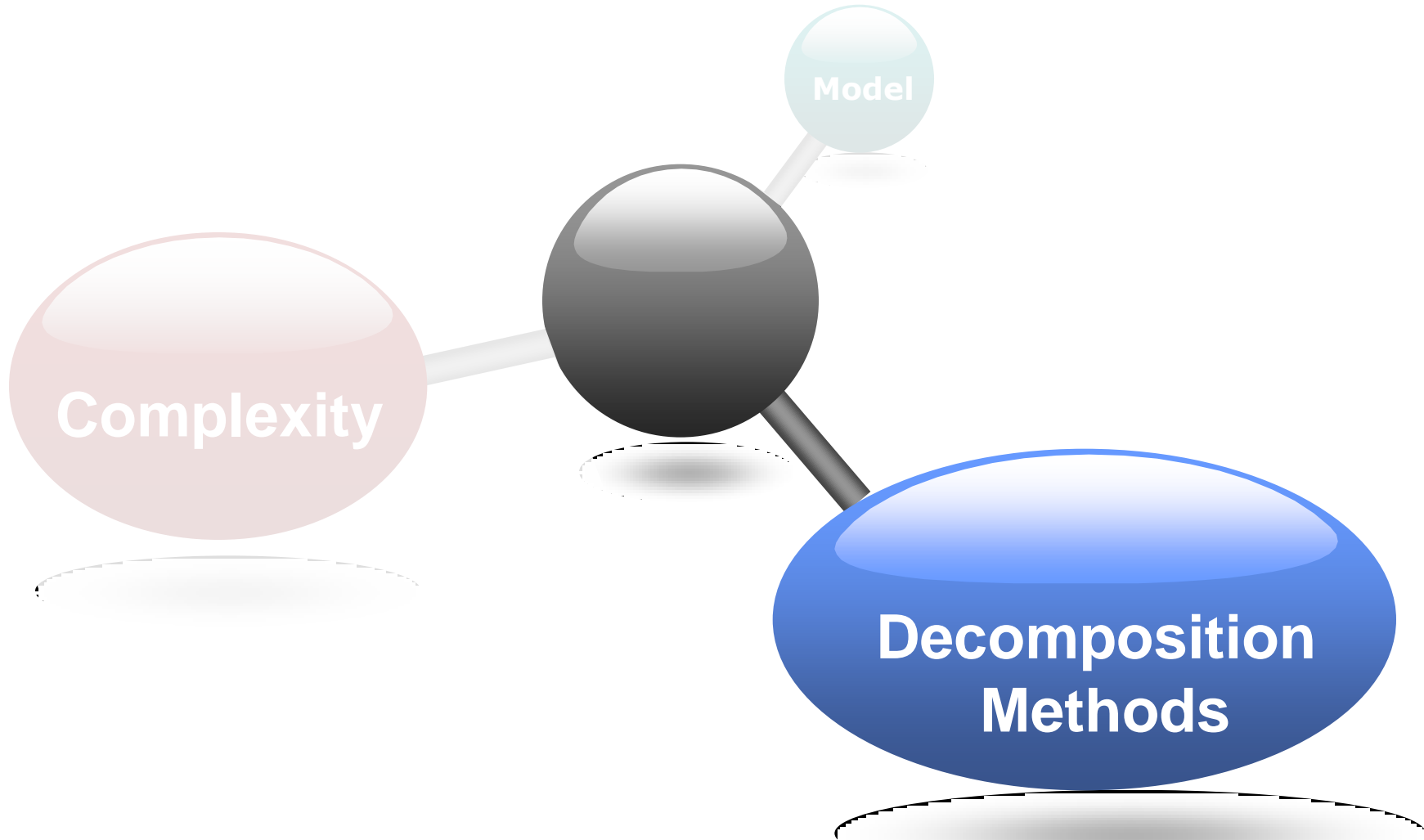
[D, F]	1	h	∞
1	in P	in P	in P
k	in P	<i>a novel machinery is needed</i>	NP-hard
∞	in P	weakly NP-hard	NP-hard

[Gottlob et al.]

- Reduction from «Partition»
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- **Restrictions on** $L = \{\mathcal{F}_1, \dots, \mathcal{F}_n\}$
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Overview



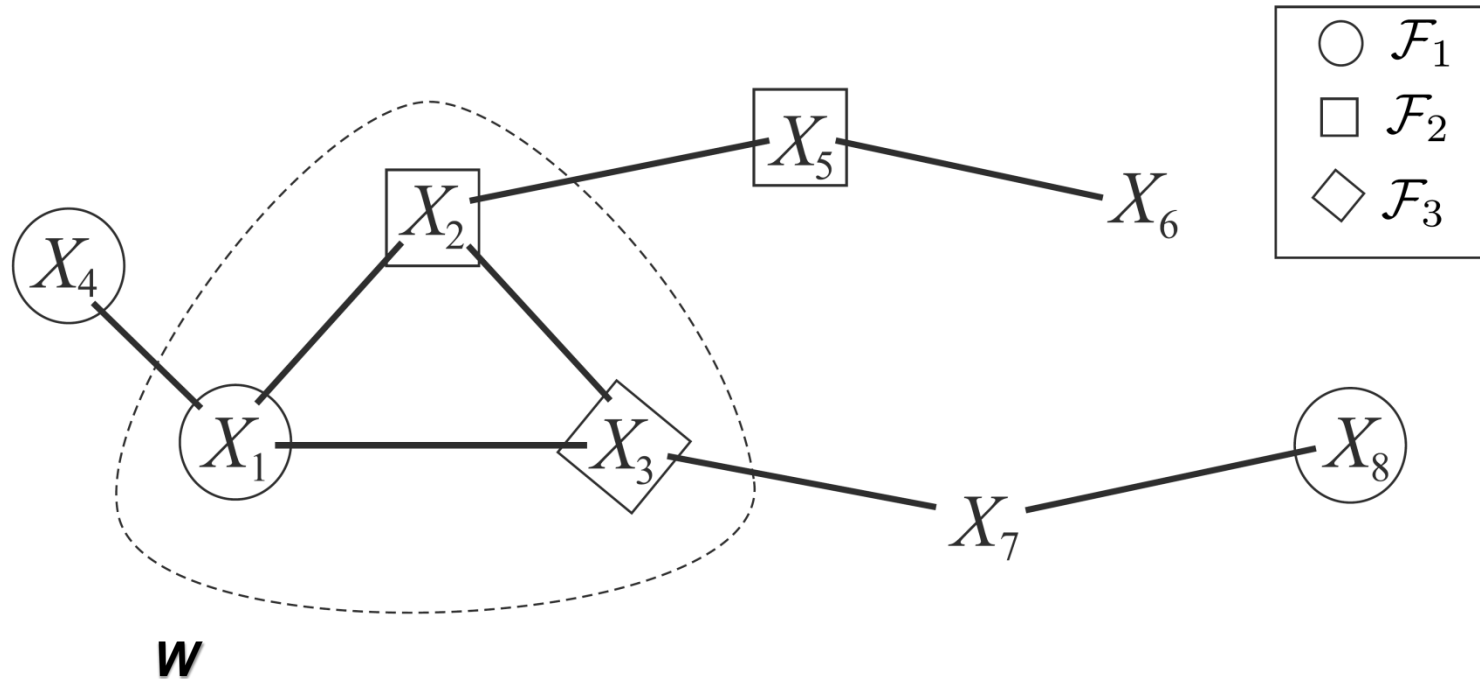
Key Ideas

Guards for Valuation Functions



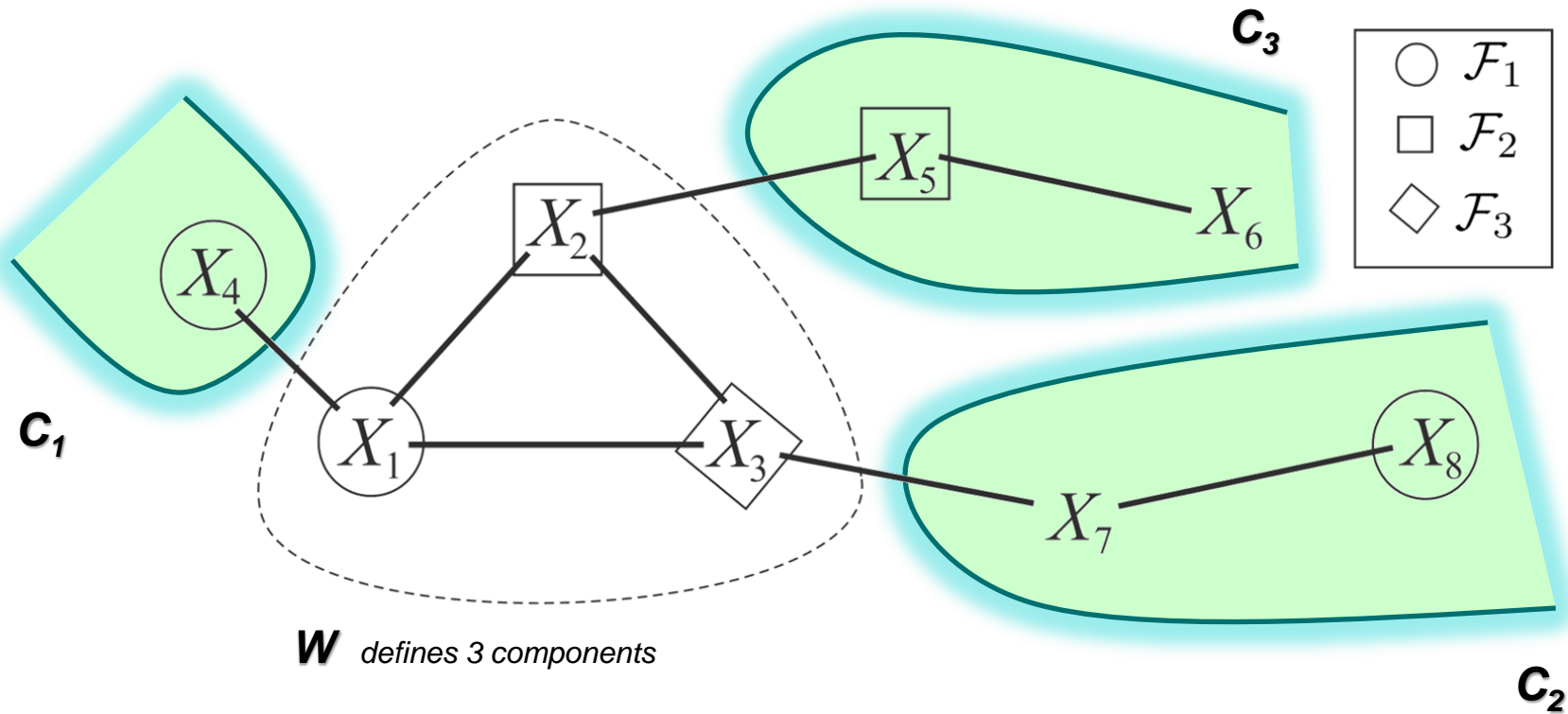
Decomposition Methods

Guards for Valuation Functions



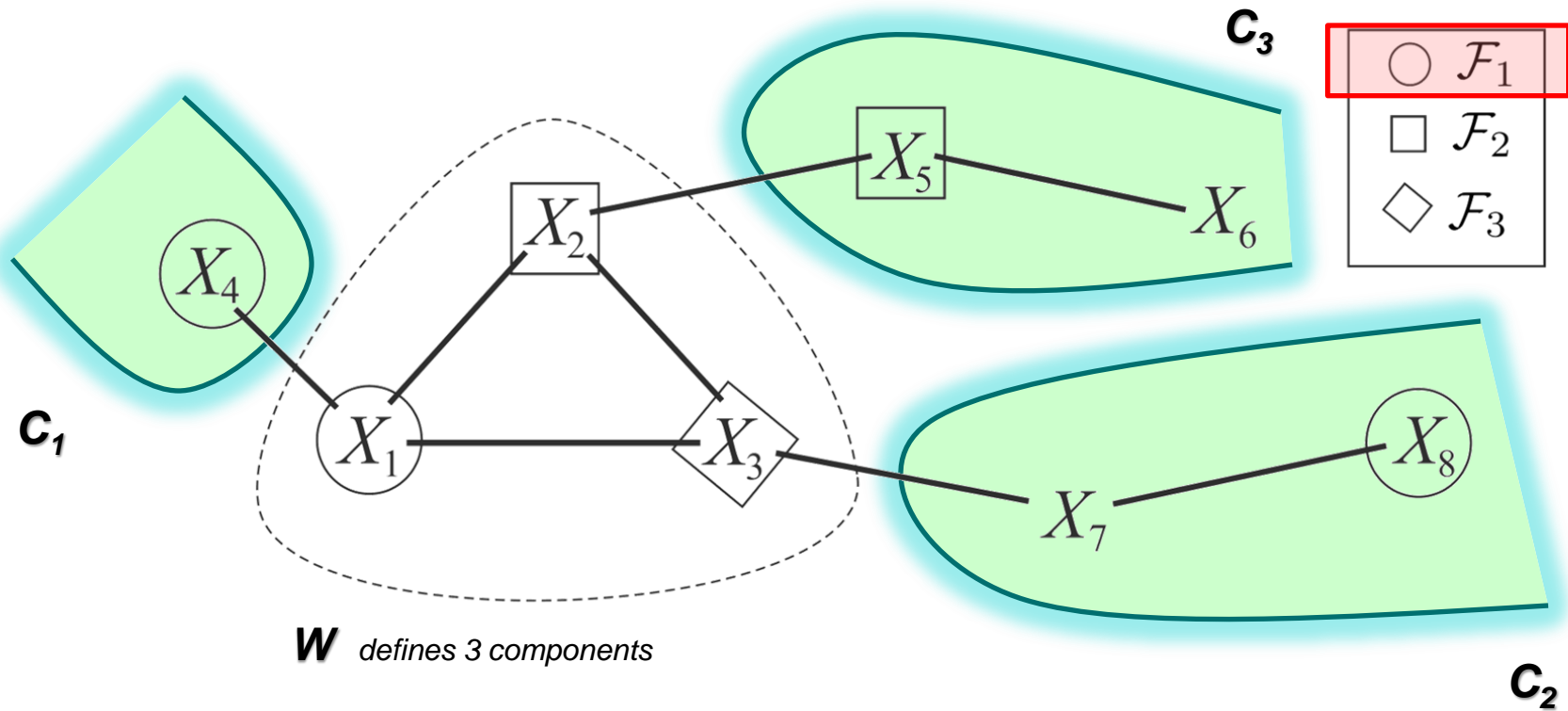
- A set of variables W is a *guard* for a valuation function if
 - separates the hypergraph in components where its domain variables do not occur together with any variable occurring in other valuation functions

Guards for Valuation Functions



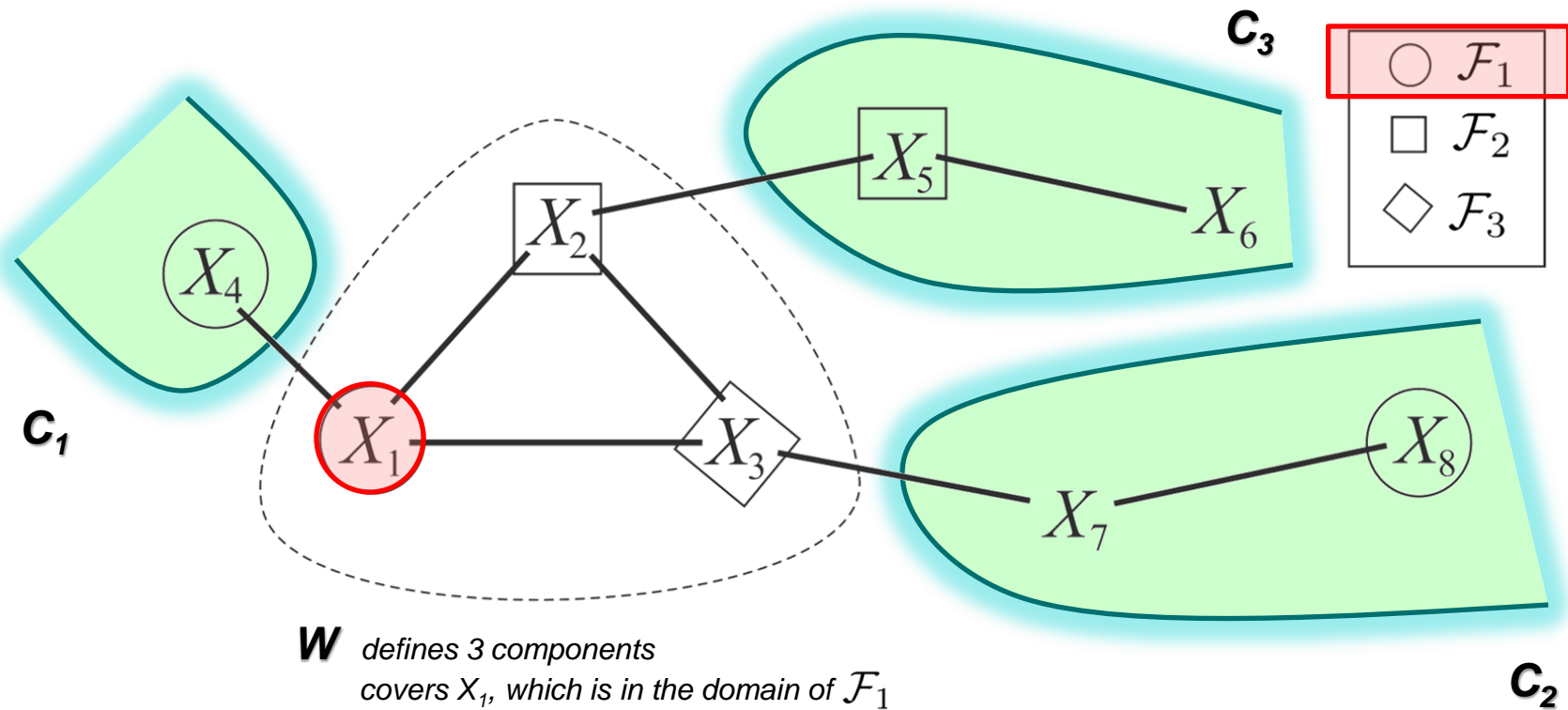
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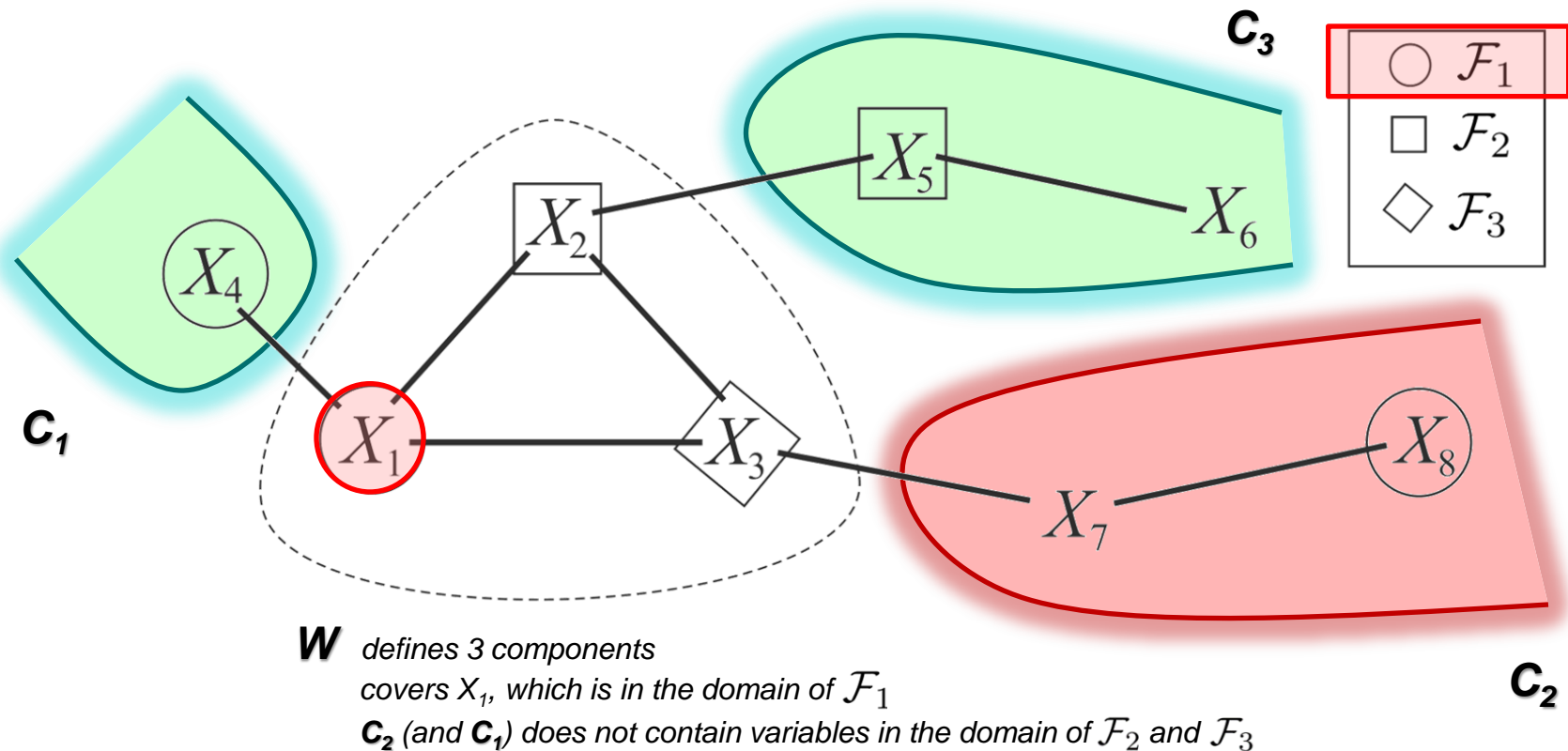
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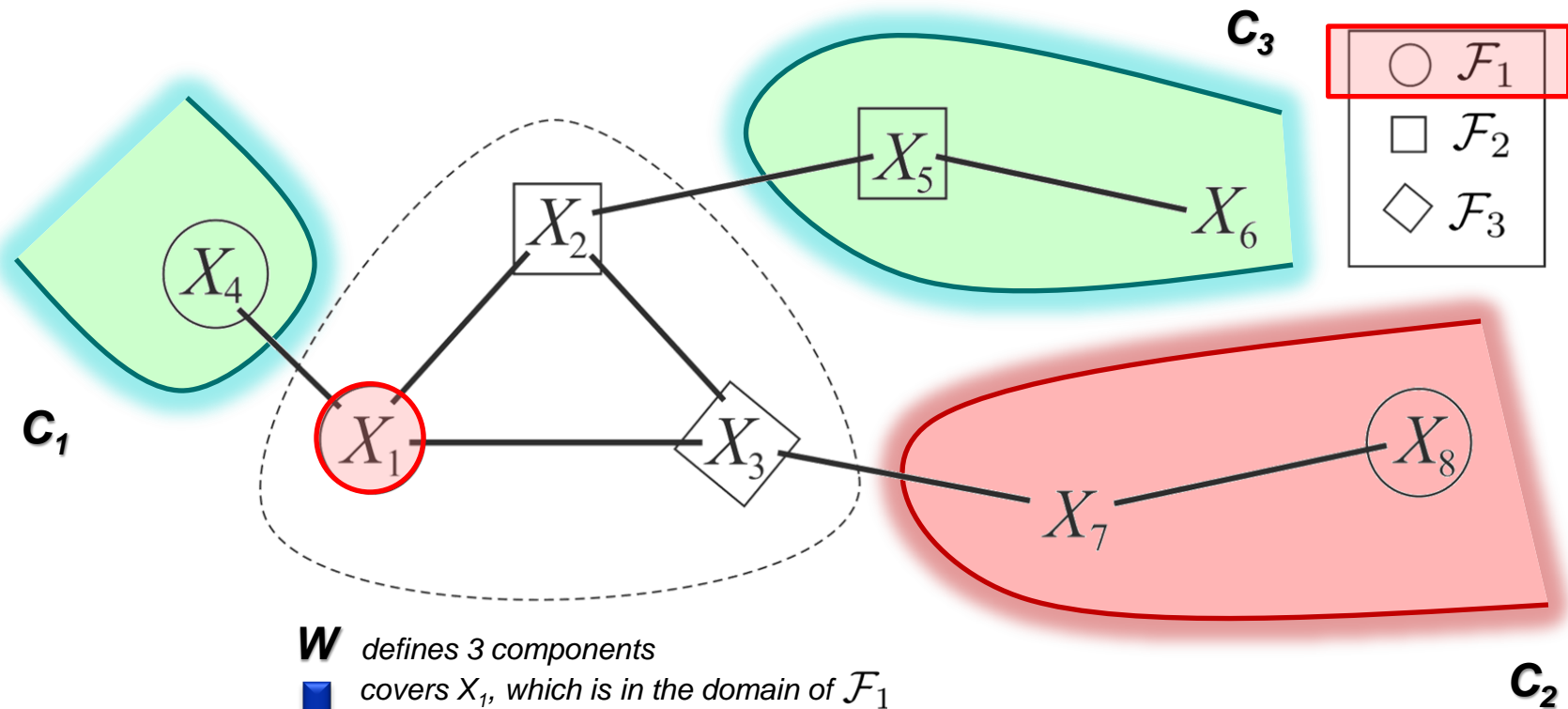
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Guards for Valuation Functions



- **A set of variables W is a *guard* for a valuation function if**
 - separates the hypergraph in components where its domain variables do not occur together with any variable occurring in other valuation functions

Guards for Valuation Functions



W defines 3 components
covers X_1 , which is in the domain of \mathcal{F}_1
 C_2 (and C_1) does not contain variables in the domain of \mathcal{F}_2 and \mathcal{F}_3

is a guard for \mathcal{F}_1 ; in fact, it is also a guard for the other functions

Key Ideas

Guards for Valuation Functions



Decomposition Methods

Decomposition Methods

■ Common Ideas

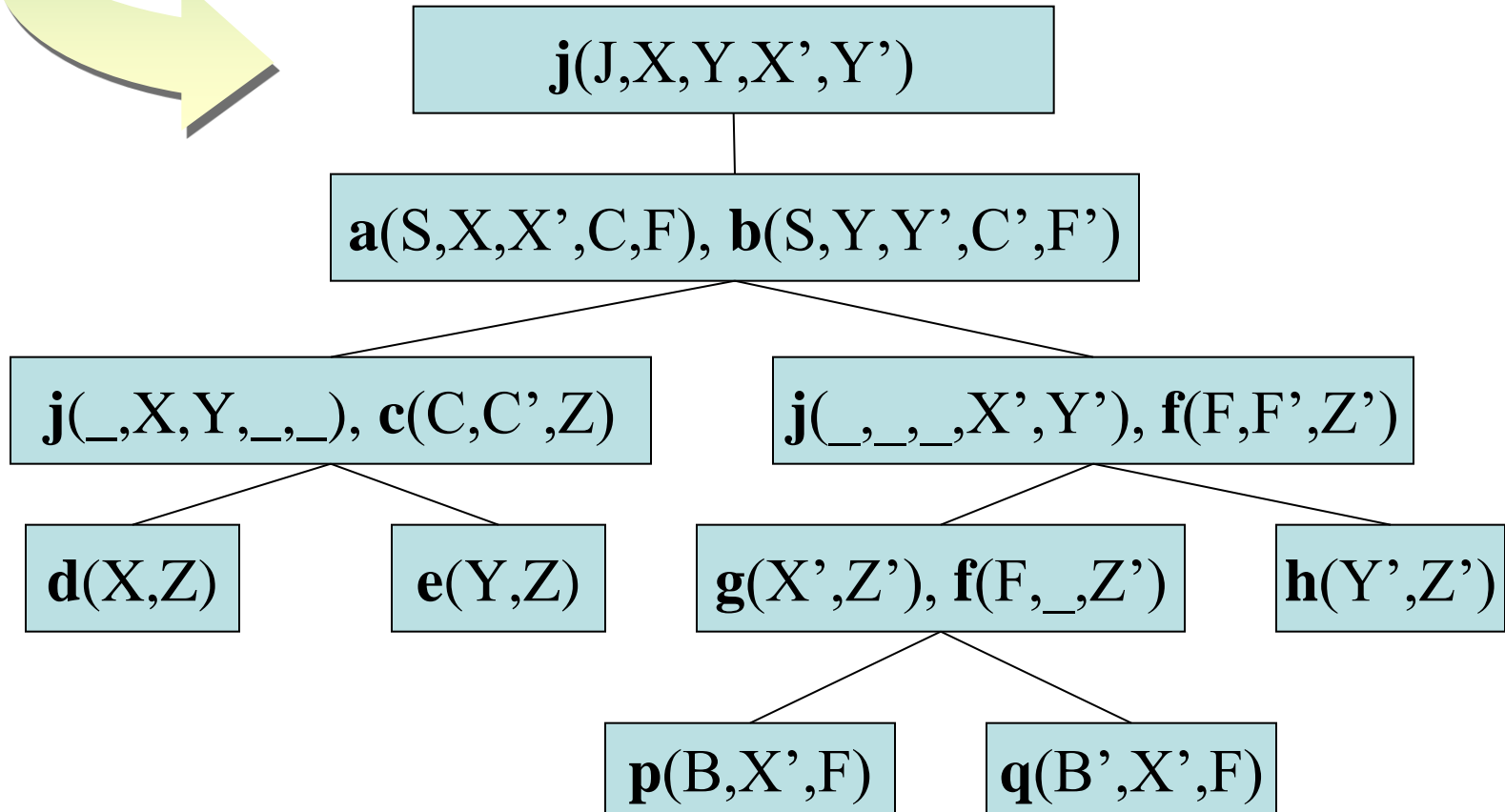
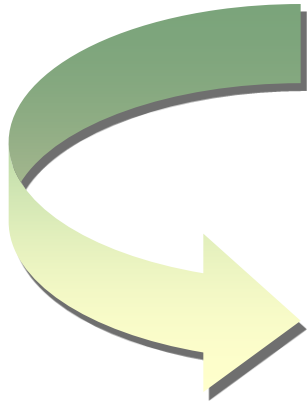
- ❑ Generalize the notion of graph or hypergraph acyclicity
- ❑ Associate a width to each instance, expressing its degree of cyclicity
- ❑ Polynomial time algorithms for bounded-width CSP instances, running in $O(n^{w+1} \cdot \log n)$
- ❑ Bounded-width CSP instances can be recognized in polynomial time
- ❑ Bounded-width decompositions can be computed in polynomial time

■ Noticeable Examples

- ❑ Tree decompositions
- ❑ (Generalized) Hypertree decompositions

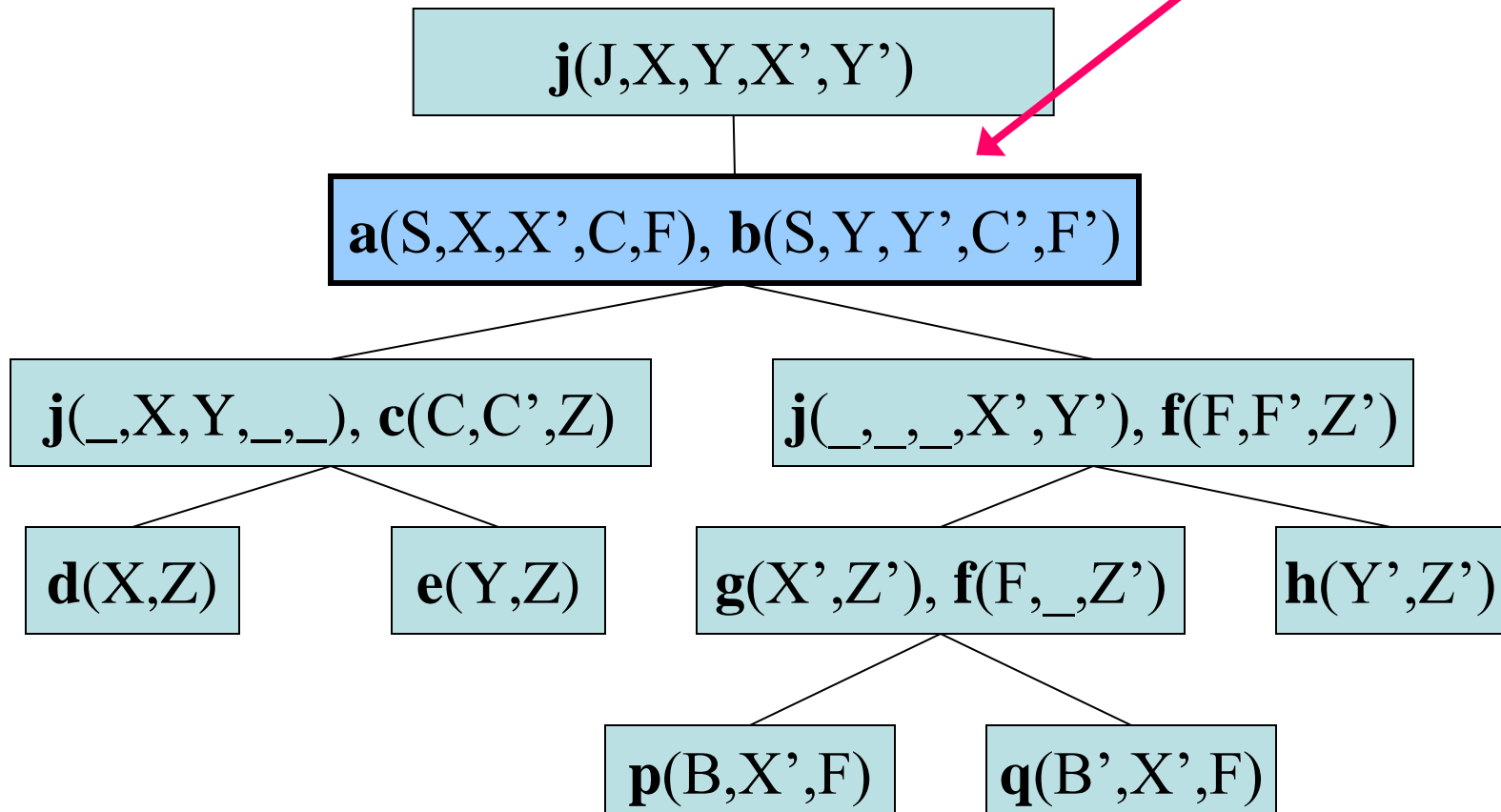
Generalized Hypertree Decompositions

$a(S, X, X', C, F)$ $b(S, Y, Y', C', F')$ $c(C, C', Z)$ $d(X, Z)$
 $e(Y, Z)$ $f(F, F', Z')$ $g(X', Z')$ $h(Y', Z')$
 $j(J, X, Y, X', Y')$ $p(B, X', F)$ $q(B', X', F)$

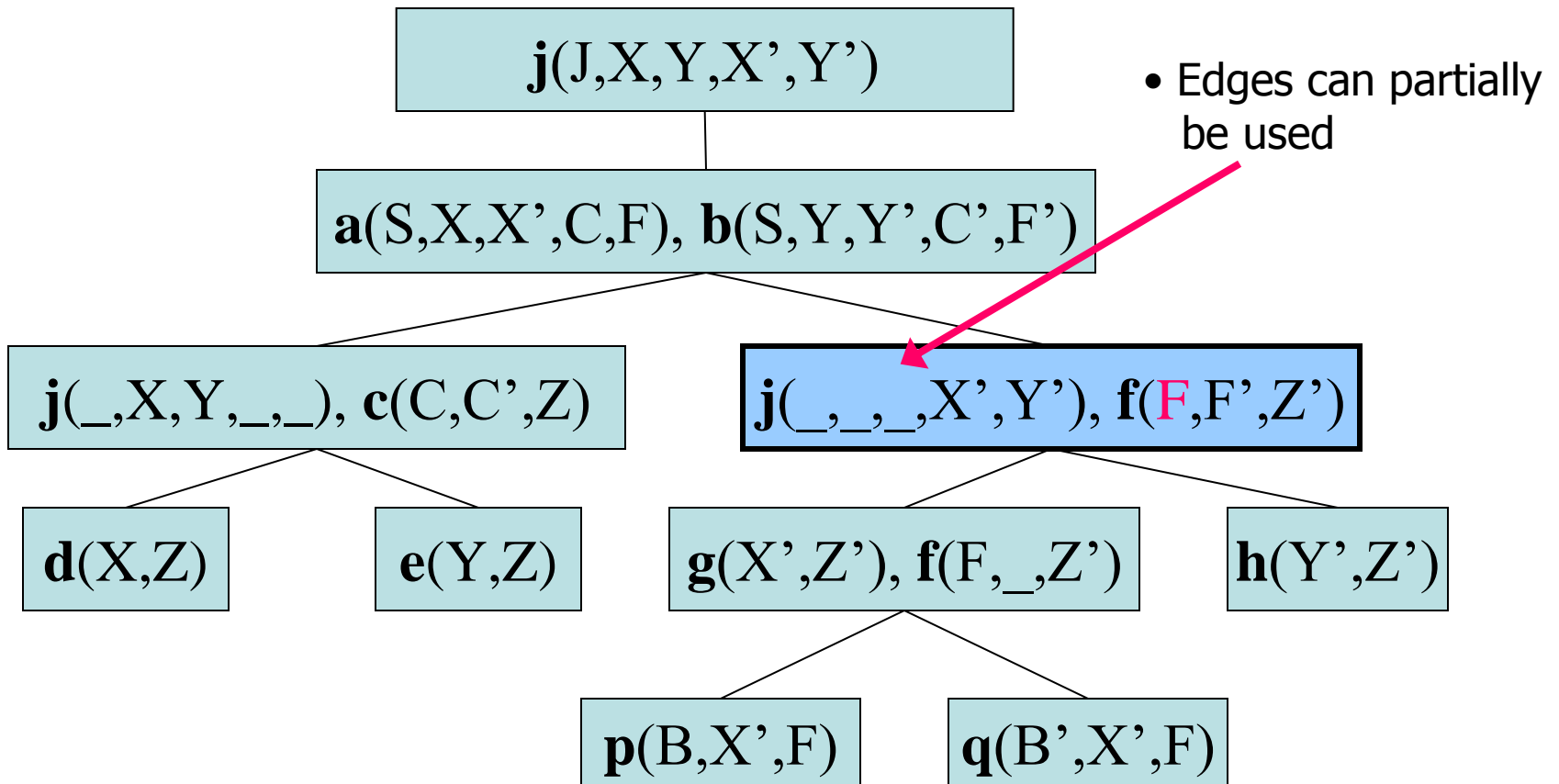


Basic Conditions_(1/2)

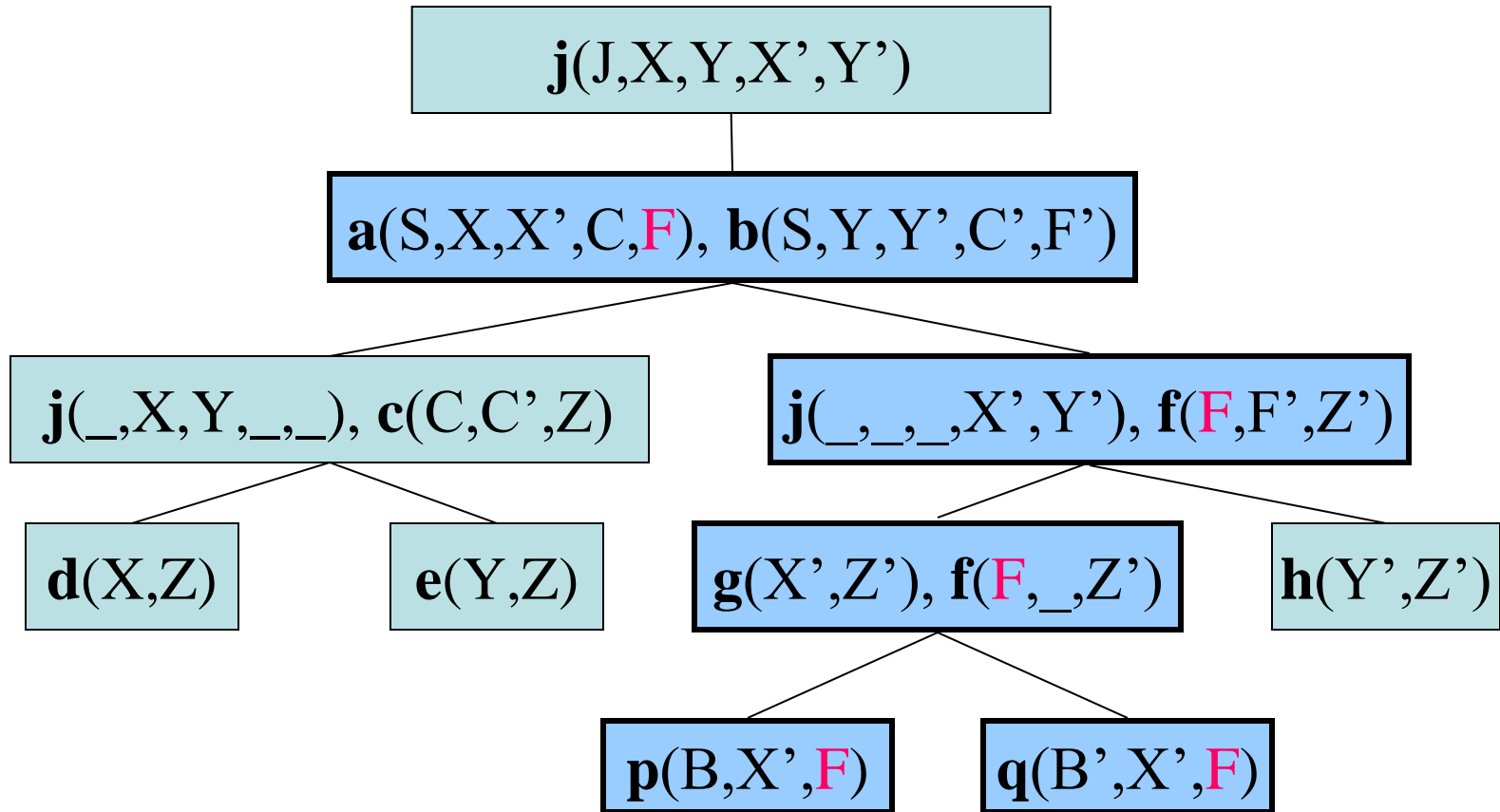
- We group edges



Basic Conditions_(2/2)

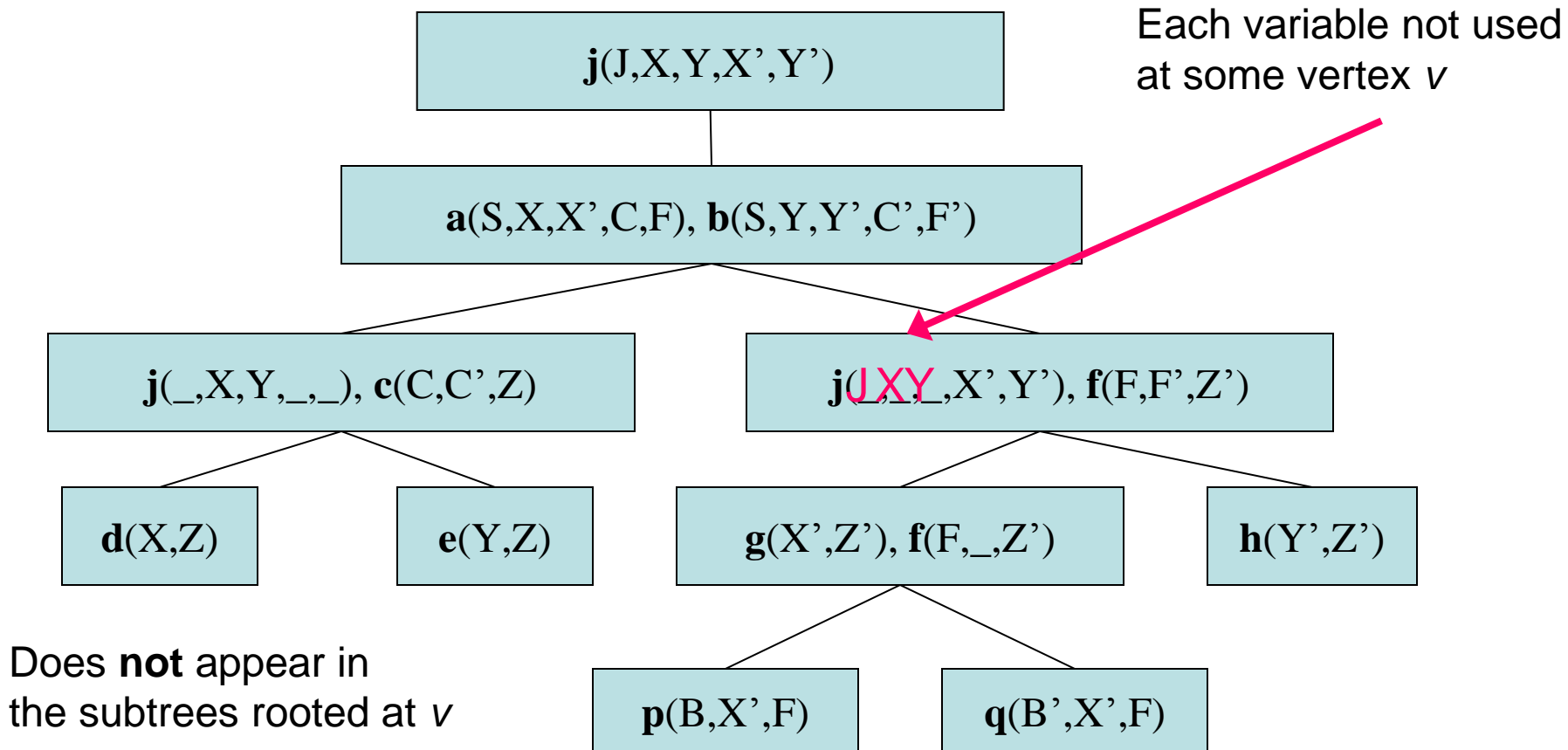


Connectdness Condition



Hypertree Decompositions (HTD)

HTD = Generalized HTD + Special Condition



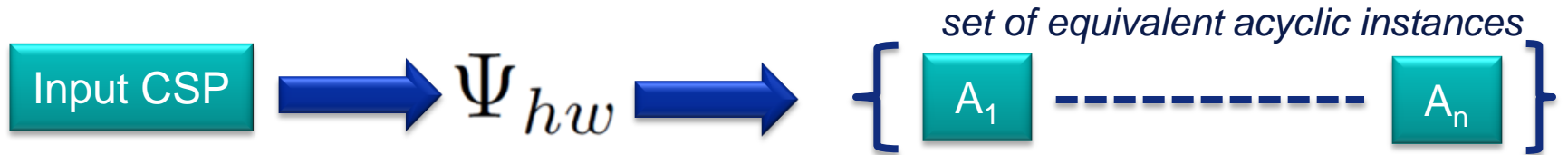
Key Ideas

Guards for Valuation Functions

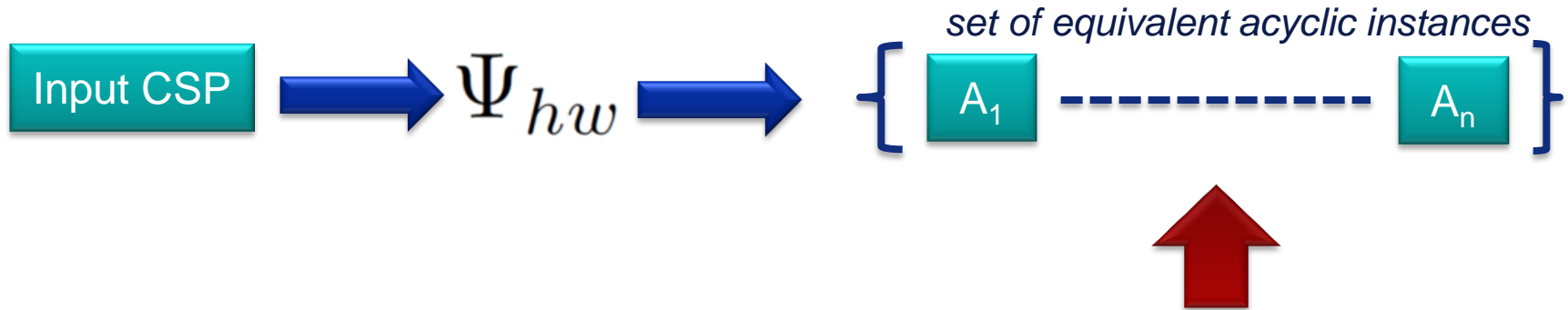


Decomposition Methods

Decomposition Methods and Guards

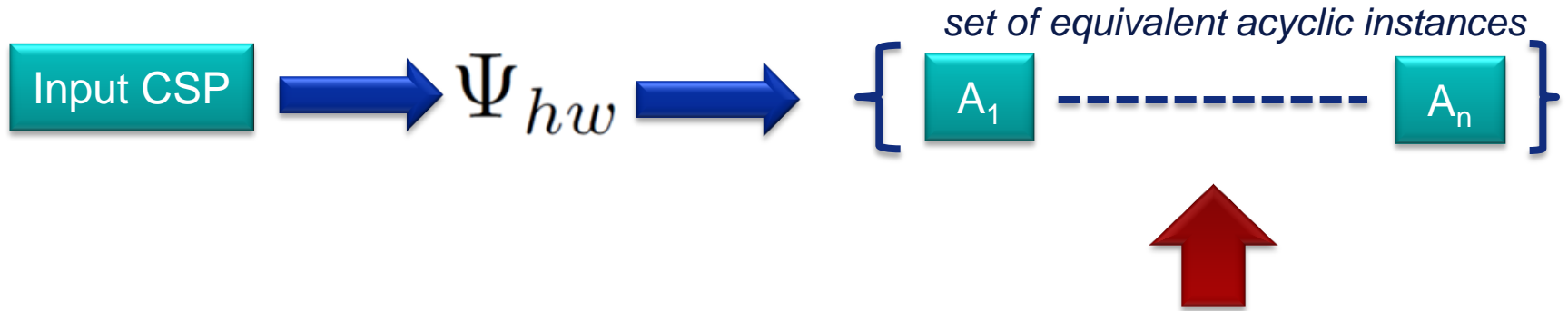


Decomposition Methods and Guards

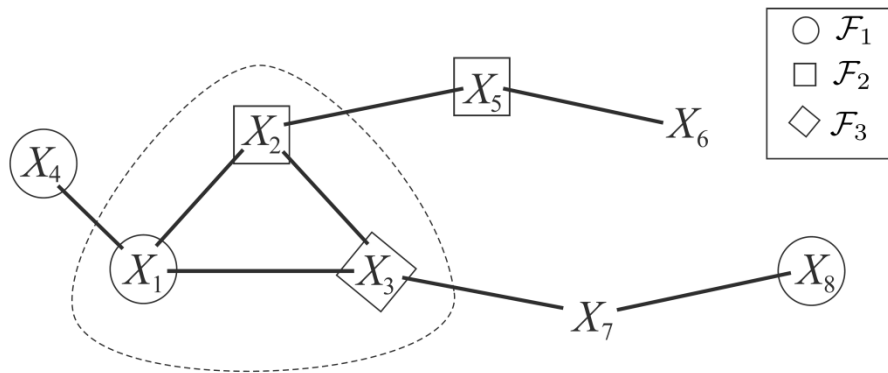


An instance is guarded via the given method if there is an output A_i such that each valuation function is guarded by some hyperedge

Decomposition Methods and Guards



An instance is guarded via the given method if there is an output A_i such that each valuation function is guarded by some hyperedge



is guarded via hypertree decomposition (width $k=3$)

Main Results

$[D, F]$	1	h	∞
1	in P	in P	in P
k	in P		NP-hard
∞	in P	weakly NP-hard	NP-hard

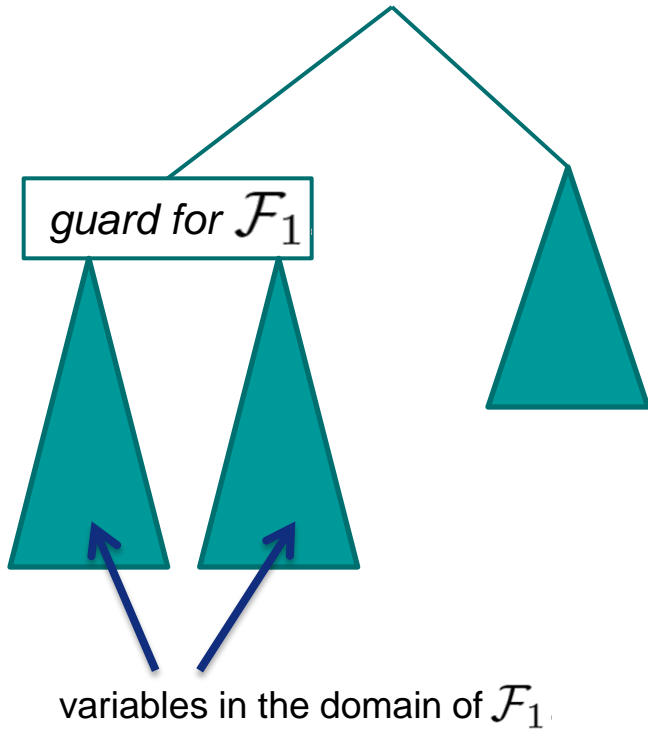
Diagram illustrating the complexity of a problem as a function of parameters $[D, F]$ and h . The table shows complexity classes (in **P**, weakly **NP-hard**, **NP-hard**) for different values of $[D, F]$ (1, k , ∞) and h (1, h , ∞). Red arrows indicate transitions: a horizontal arrow from ∞ to h in the top row, and vertical arrows pointing up from k to 1 and down from ∞ to k in the first column.

Main Results

$[D, F]$	1	h	∞
1	in \mathbf{P}	in \mathbf{P}	in \mathbf{P}
k	in \mathbf{P}		NP-hard
∞	in \mathbf{P}	weakly NP-hard	NP-hard

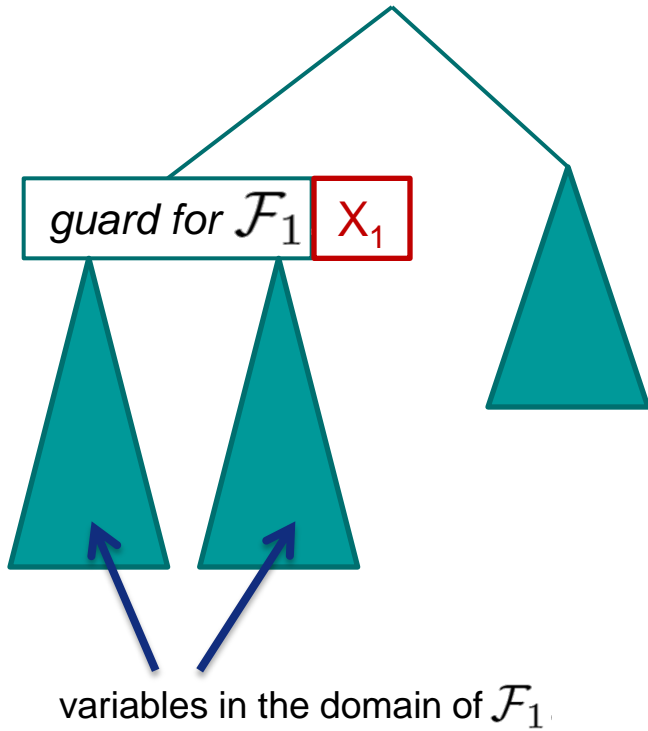
in \mathbf{P} , if guarded via Ψ_{hw}

Proof Idea



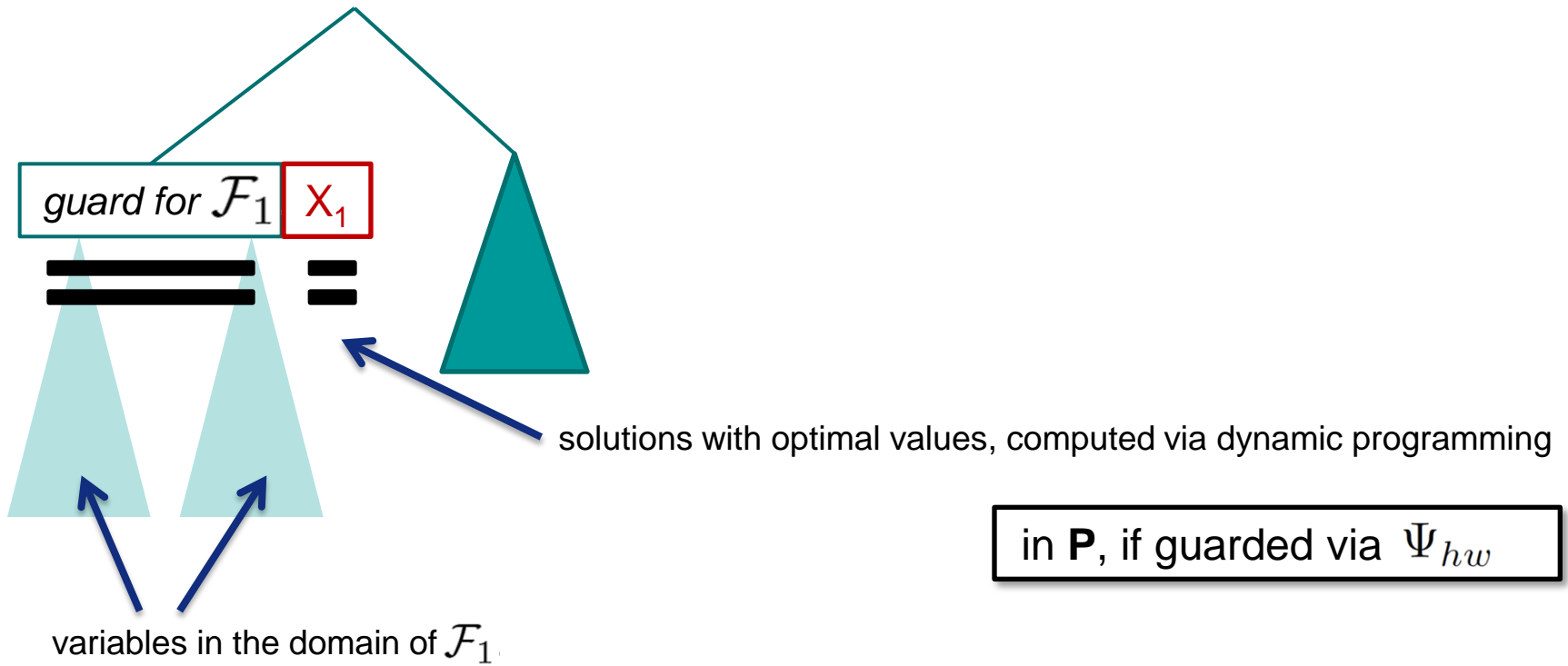
in \mathbf{P} , if guarded via Ψ_{hw}

Proof Idea

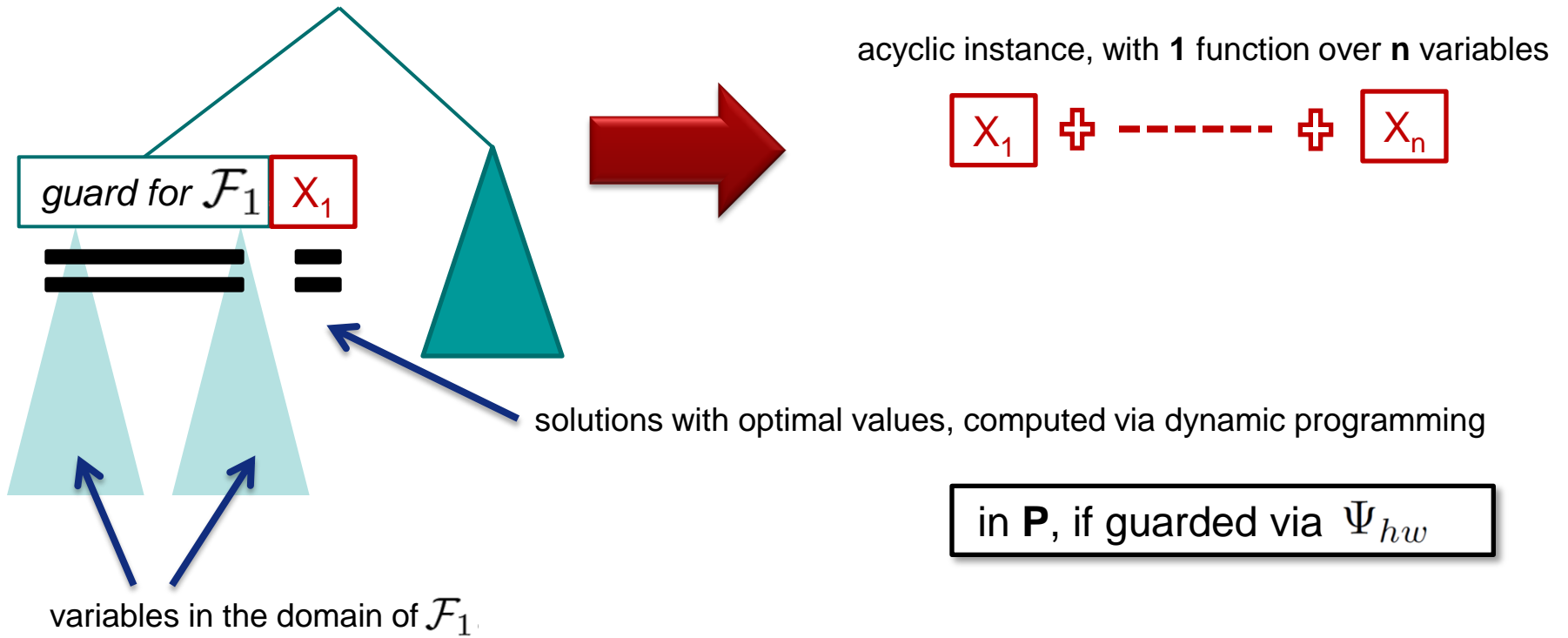


in \mathbf{P} , if guarded via Ψ_{hw}

Proof Idea



Proof Idea



Main Results

$[D, F]$	1	h	∞
1	in \mathbf{P}	in \mathbf{P}	in \mathbf{P}
k	in \mathbf{P}		NP-hard
∞	in \mathbf{P}	weakly NP-hard	NP-hard

in \mathbf{P} , if guarded via Ψ_{hw}

Main Results

$[D, F]$	1	h	∞
1	in \mathbf{P}	in \mathbf{P}	in \mathbf{P}
k	in \mathbf{P}	weakly NP-hard	NP-hard
∞	in \mathbf{P}		NP-hard

in \mathbf{P} , if guarded via Ψ_{hw}

(acyclic) instances of this kind are always guarded via Ψ_{hw} width: $h \times k+1$

Main Results

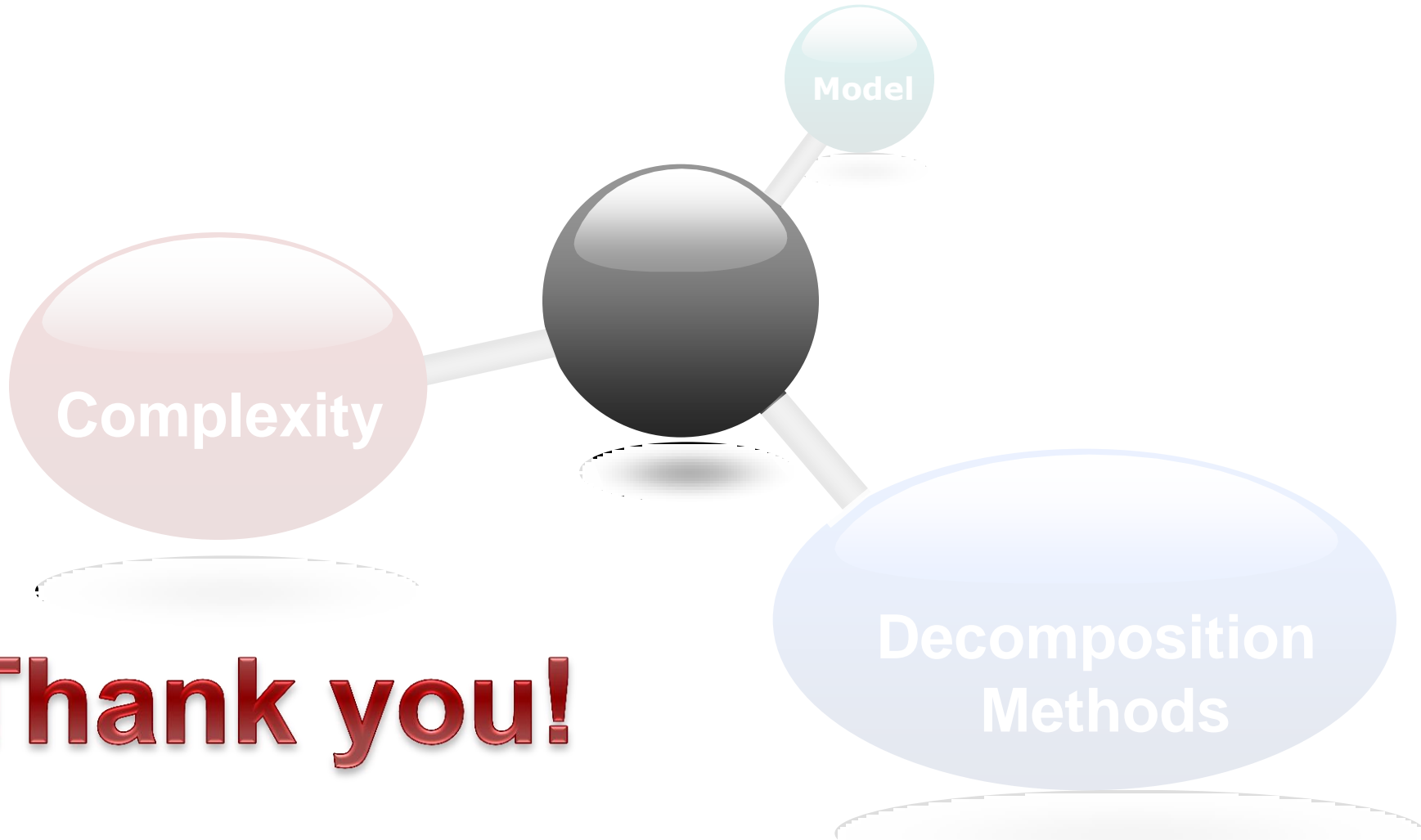
$[D, F]$	1	h	∞
1	in P	in P	in P
k	in P	in P	NP-hard
∞	in P	weakly NP-hard	NP-hard

in **P**, if guarded via Ψ_{hw}



(acyclic) instances of this kind are always guarded via Ψ_{hw} width: $h \times k+1$

Overview



Thank you!