

and Practice

Game Theory for Society and Economy

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AI and Society?



SOCIETY AND ECONOMY

AI and Society?



ARTIFICIAL INTELLIGENCE



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GAME THEORY

ARTIFICIAL INTELLIGENCE

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GAME THEORY



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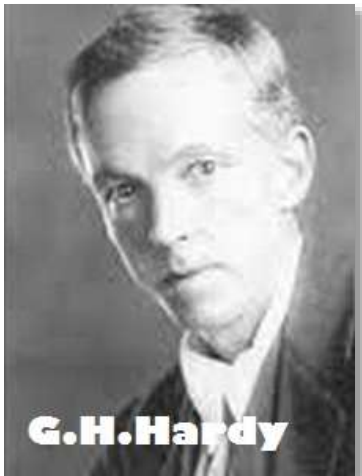
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G.H. Hardy

Apologia di un matematico, 1940:

Non ho mai fatto nulla di «utile». Nessuna mia scoperta ha contribuito, e verosimilmente mai lo farà, ad apportare il benché minimo miglioramento, diretto o indiretto, al benessere dell'umanità. [...] Giudicato dal punto di vista della rilevanza pratica, il valore della mia vita matematica è nullo. [...] La sola difesa della mia vita è questa: Ho aggiunto qualcosa al sapere e ho aiutato altri ad aumentarlo ancora; il valore dei miei contributi si differenzia soltanto in grado, e non in natura, dalle creazioni dei grandi matematici, o di tutti gli altri artisti, grandi e piccoli, che hanno lasciato qualche traccia dietro di loro.

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GAME THEORY



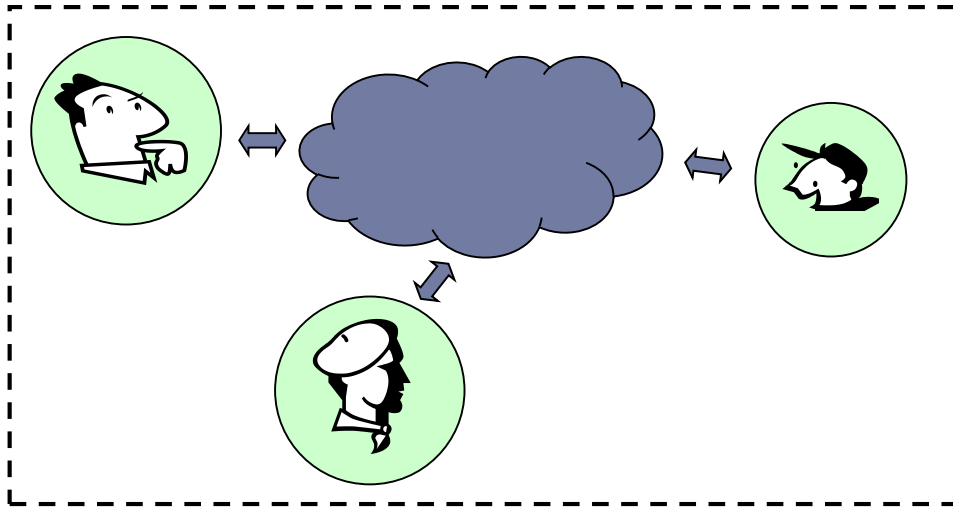
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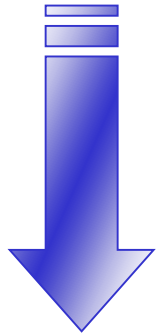
Game Theory



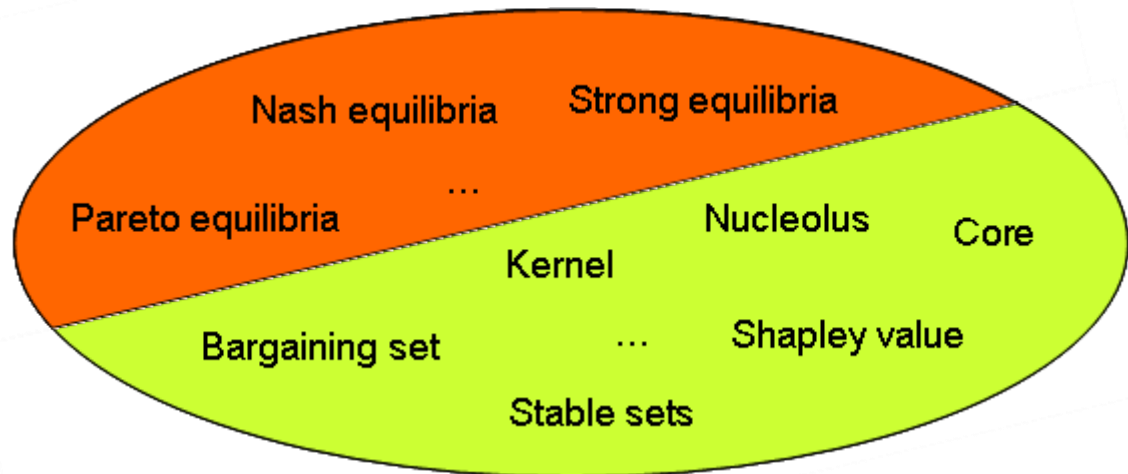
Each player:

- Has a **goal** to be achieved
- Has a set of possible **actions**
- **Interacts** with other players
- Is **rational**

Which actions have to be performed?



Solution Concepts

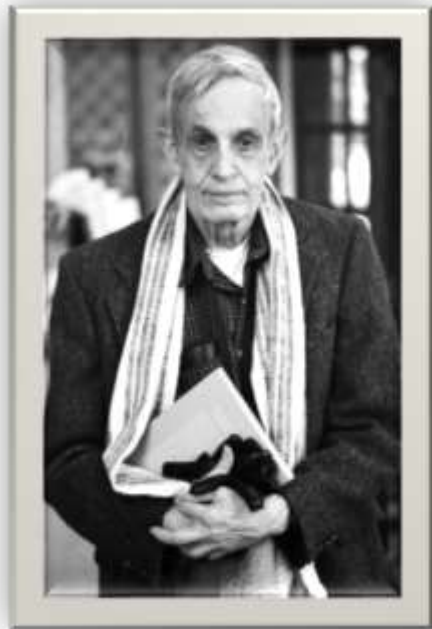


Two Perspectives

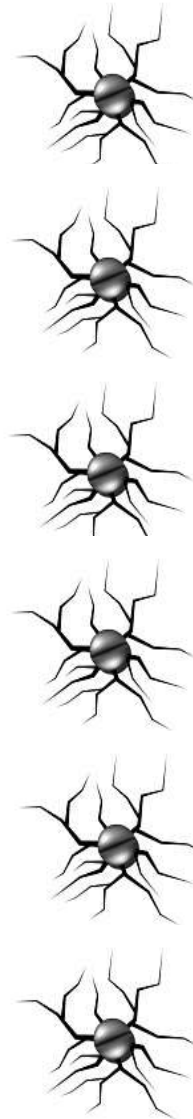


▶ Strategic Games

- ▶ Agents are selfish interested



JOHN NASH



▶ Coalitional Games

- ▶ Agents can collaborate



JOHN VON NEUMANN

STRATEGIC GAMES



Non-Cooperative Games



Payoff maximization problem

Each player:

- Has a **goal** to be achieved
- Has a set of possible **actions**
- **Interacts** with other players
- Is **rational**

Bob	John goes <i>out</i>	John stays at <i>home</i>
<i>out</i>	2	0
<i>home</i>	0	1

John	Bob goes <i>out</i>	Bob stays at <i>home</i>
<i>out</i>	1	1
<i>home</i>	0	0

Non-Cooperative Games



Payoff maximization problem

Nash equilibria

Each player:

- Has a **goal** to be achieved
- Has a set of possible **actions**
- **Interacts** with other players
- **Is rational**

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Non-Cooperative Games



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Non-Cooperative Games



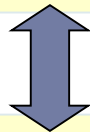
Payoff maximization problem

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- Is **rational**

Nash equilibria

pure Nash equilibria



Every game admits a mixed Nash equilibrium,

- where players chose their strategies according to probability distributions

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Game Representations



- ▶ **Players:**
 - ▶ Maria, Francesco
- ▶ **Choices:**
 - ▶ movie, opera

If 2 players, then size = 2^2

Maria	Francesco, <i>movie</i>	Francesco, <i>opera</i>
<i>movie</i>	2	0
<i>opera</i>	0	1

Game Representations



- ▶ **Players:**
 - ▶ Maria, Francesco, Paola
- ▶ **Choices:**
 - ▶ movie, opera

If 2 players, then size = 2^2

If 3 players, then size = 2^3

Maria	F _{movie} and P _{movie}	F _{movie} and P _{opera}	F _{opera} and P _{movie}	F _{opera} and P _{opera}
movie	2	0	2	1
opera	0	1	2	2

Game Representations



- ▶ **Players:**
 - ▶ Maria, Francesco, Paola, Roberto, and Giorgio
- ▶ **Choices:**
 - ▶ movie, opera

If 2 players, then size = 2^2

If 3 players, then size = 2^3

...

If N players, then size = 2^N

Maria	F _{movie} and P _{movie} and R _{movie} and G _{movie}			
<i>movie</i>	2
<i>opera</i>	0

Game Representations



▶ Game Representation

- ▶ Tables
- ▶ Arbitrary Functions

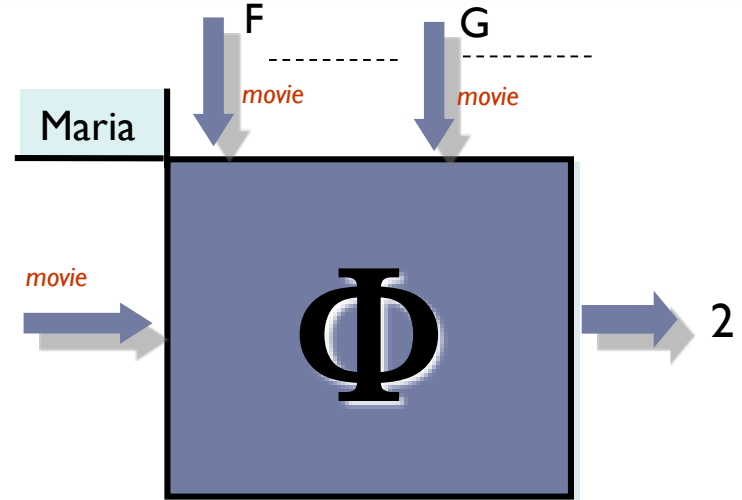
Maria	F_{movie} and P_{movie} and R_{movie} and G_{movie}			
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Game Representations



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- ▶ Tables
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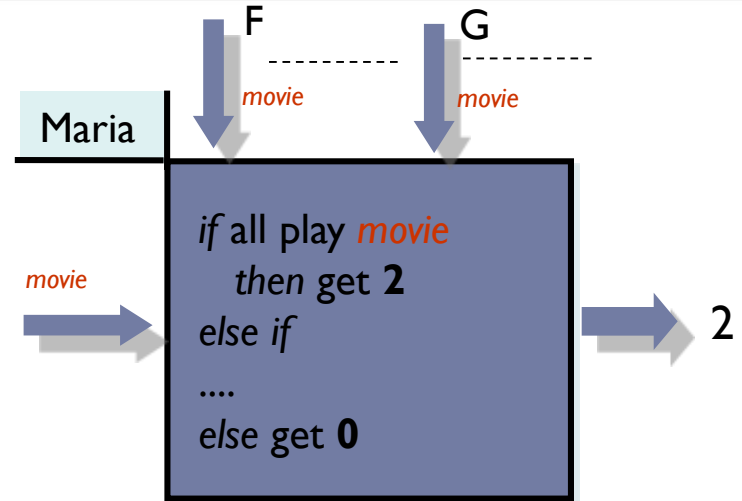
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<i>movie</i>	2
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Game Representations



▶ Game Representation

- ▶ Tables
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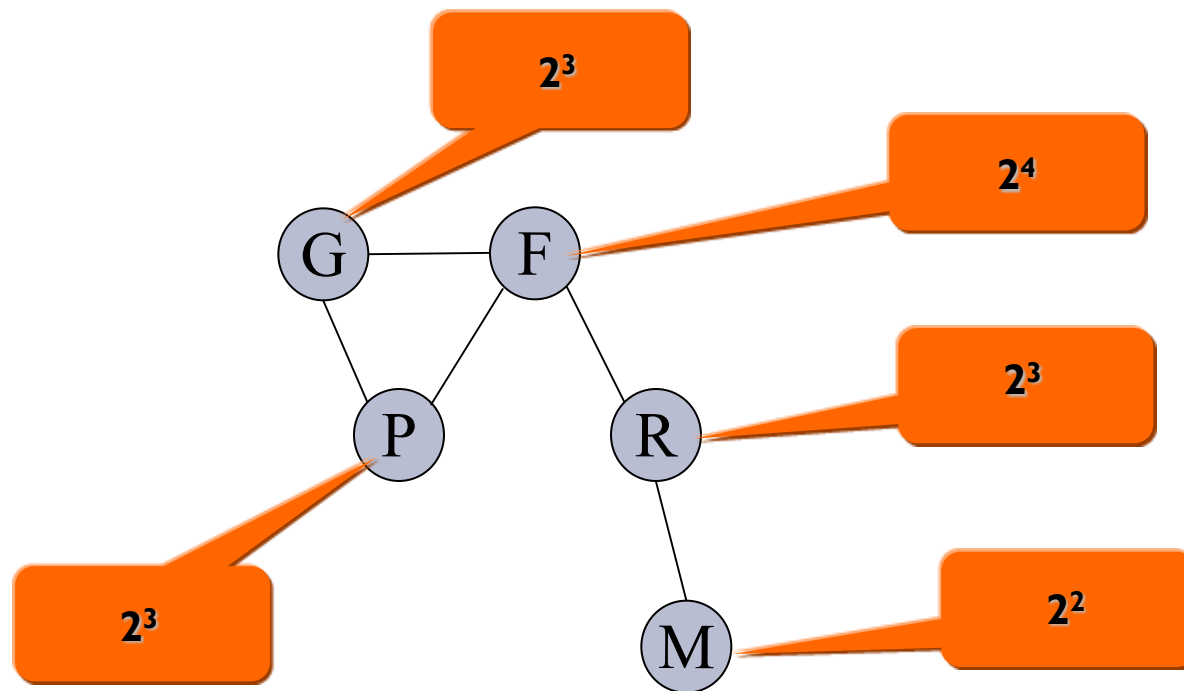


Maria	F_{movie} and P_{movie} and R_{movie} and G_{movie}			
<i>movie</i>	2
<i>opera</i>	0

Game Representations



- ▶ **Players:**
 - ▶ Francesco, Paola, Roberto, Giorgio, and Maria
- ▶ **Choices:**
 - ▶ movie, opera



Games on Graphs

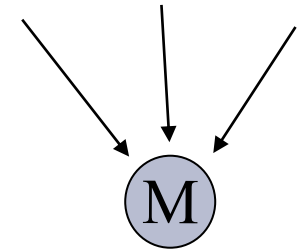


▶ Game Representation

- ▶ ~~Tables~~
- ▶ ~~Arbitrary Functions~~

▶ Neighborhood

- ▶ Arbitrary
- ▶ Small (i.e., log)
- ▶ Bounded (i.e., constant)



Games on Graphs



▶ Game Representation

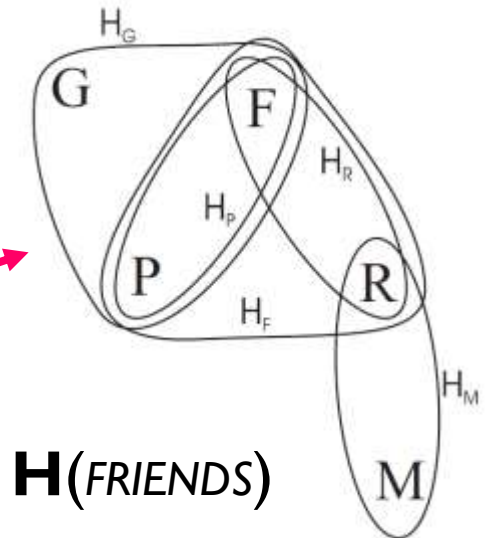
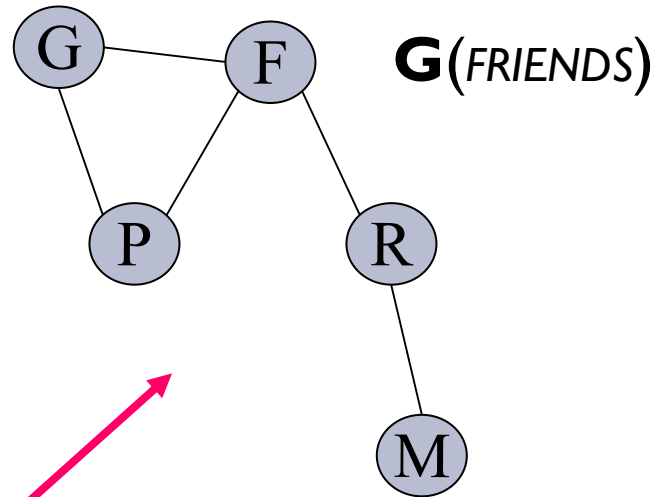
- ▶ ~~Tables~~
- ▶ ~~Arbitrary Functions~~

▶ Neighborhood

- ▶ Arbitrary
- ▶ Small (i.e., log)
- ▶ Bounded (i.e., constant)

▶ Interactions

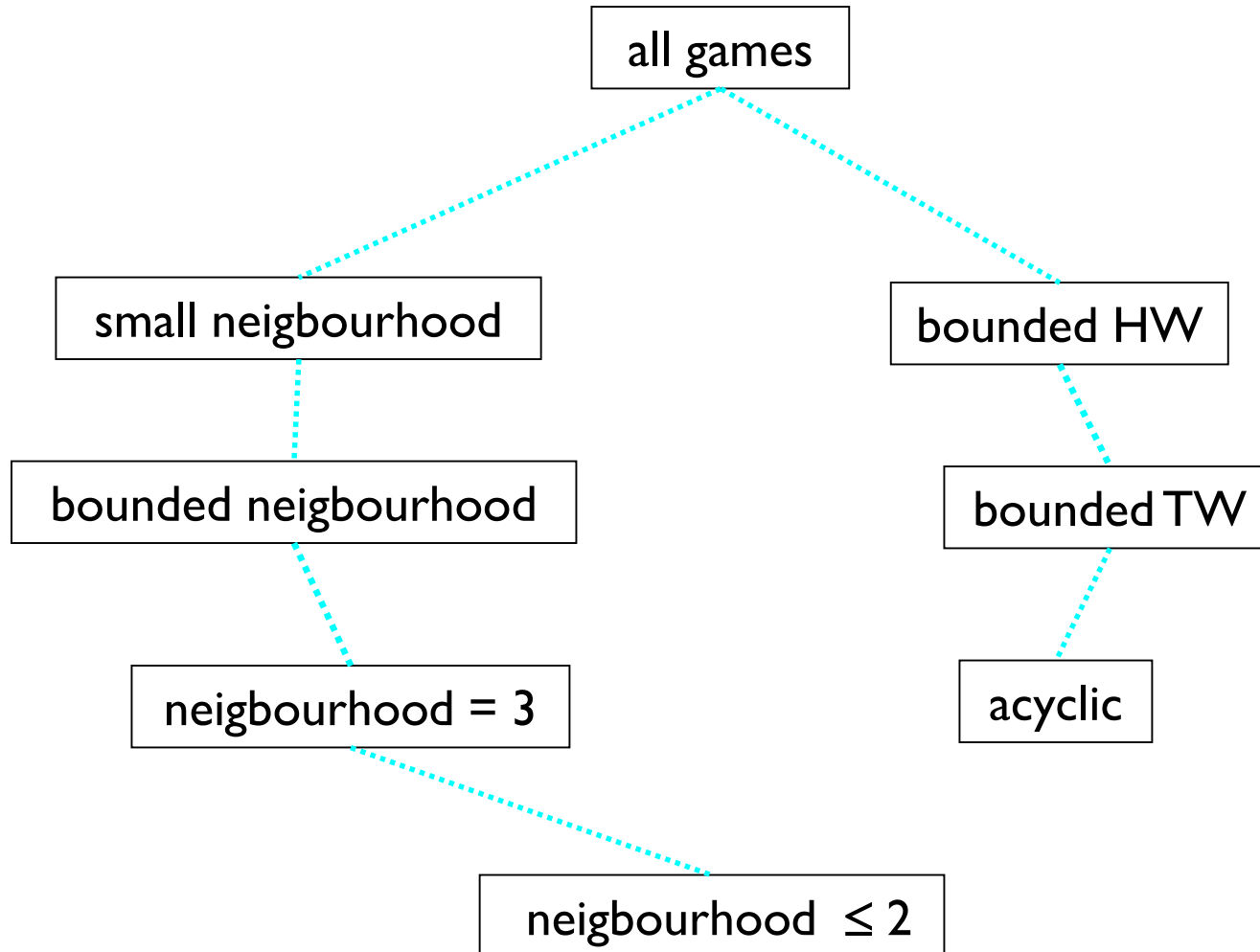
- ▶ Game graph G :
 - ▶ acyclic or *bounded treewidth*
- ▶ Game hypergraph H :
 - ▶ acyclic or *bounded hypertreewidth*



Results [GG5'05]



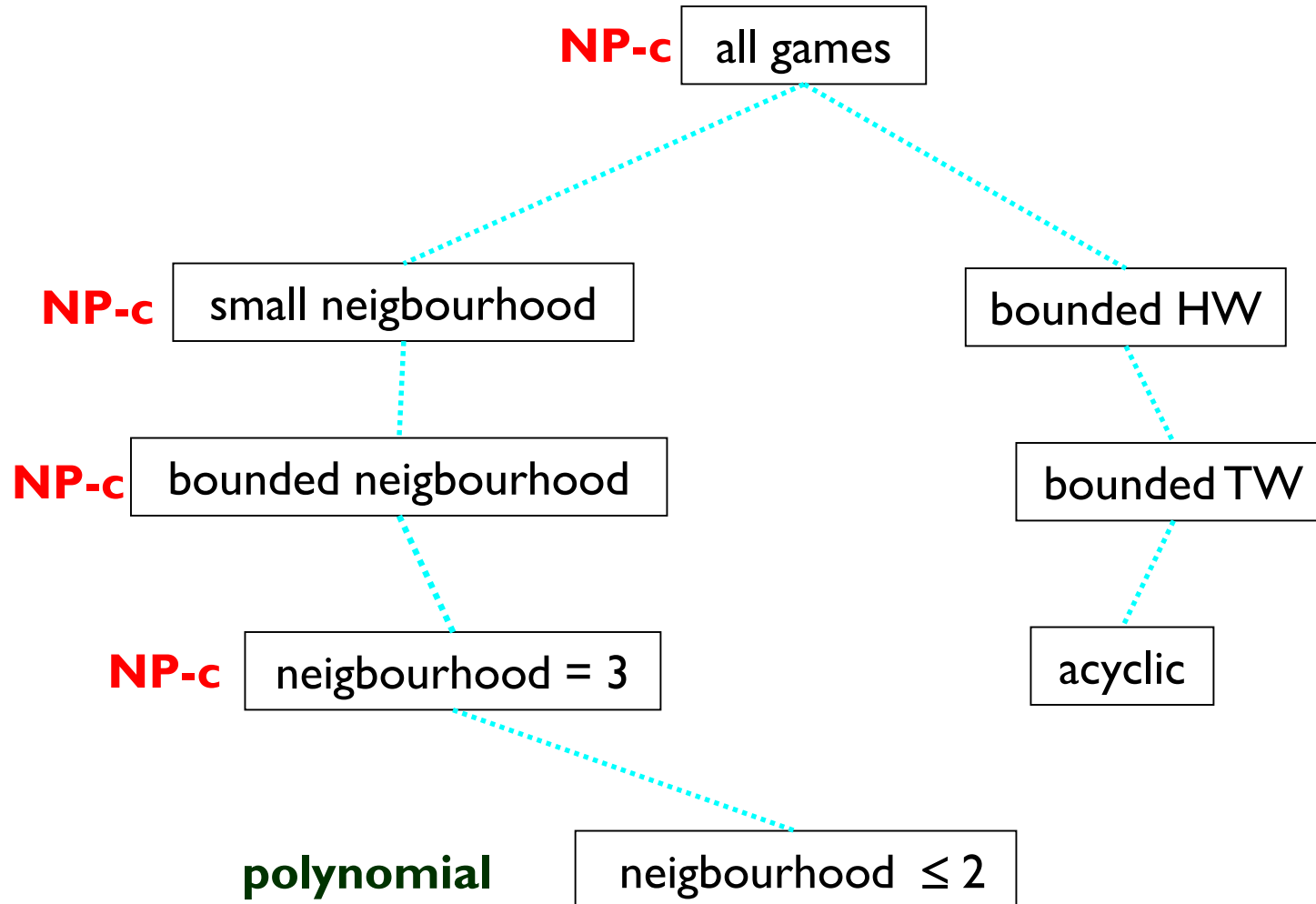
[G., Gottlob, Scarcello JAIR'05]



Results [665'05]



THE BAD NEWS:

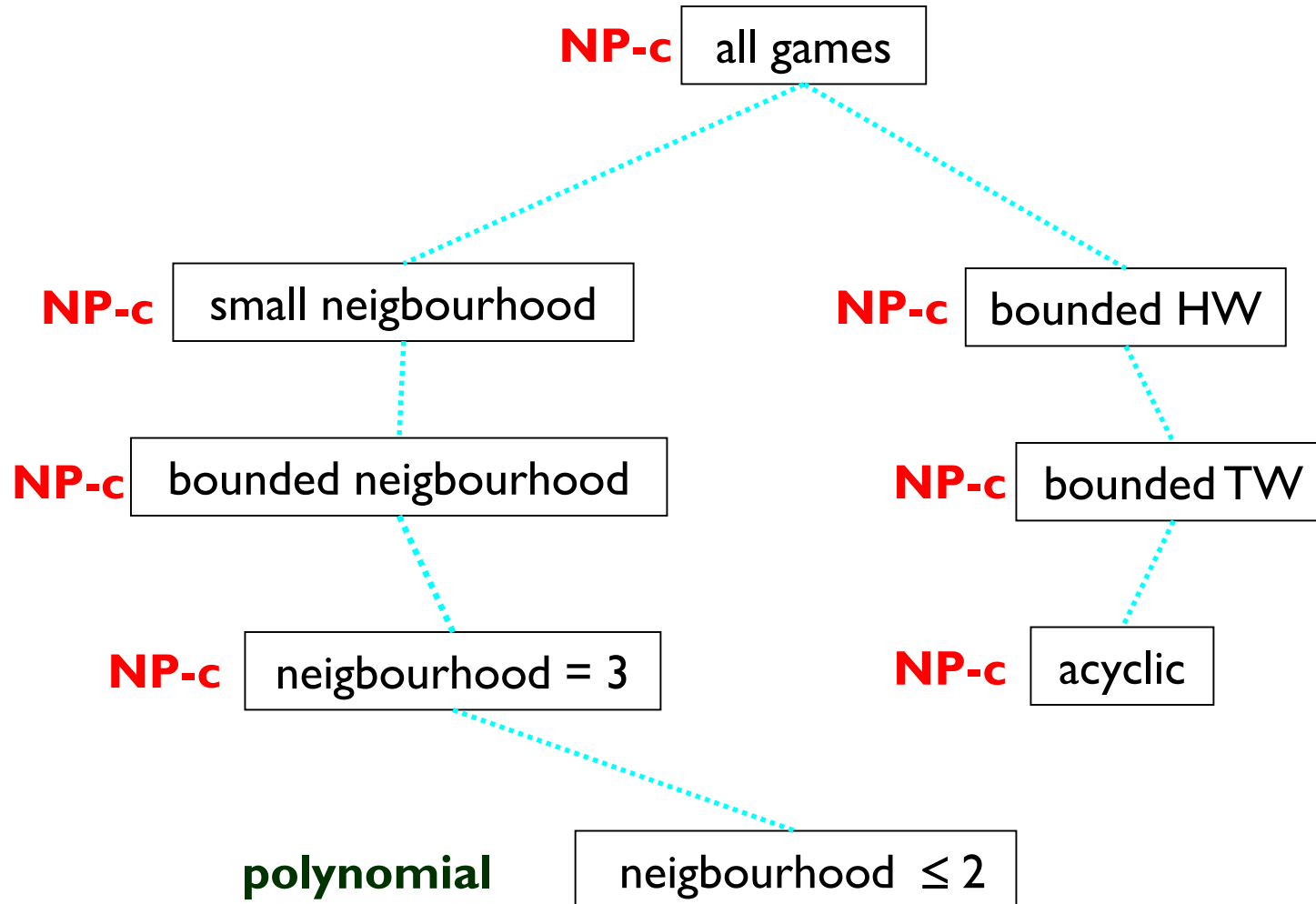


Results [665'05]



THE BAD NEWS:

FURTHER BAD NEWS:



Results [GG5'05]



THE GOOD NEWS:

CSP techniques



NP-c all games

NP-c small neighbourhood

NP-c bounded HW

NP-c bounded neighbourhood

NP-c bounded TW

NP-c neighbourhood = 3

NP-c acyclic

polynomial

neighbourhood ≤ 2

Results [GG5'05]



THE GOOD NEWS:

CSP techniques



NP-c all games

NP-c small neighbourhood

NP-c bounded HW

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neighbourhood = 3

\wedge

acyclic

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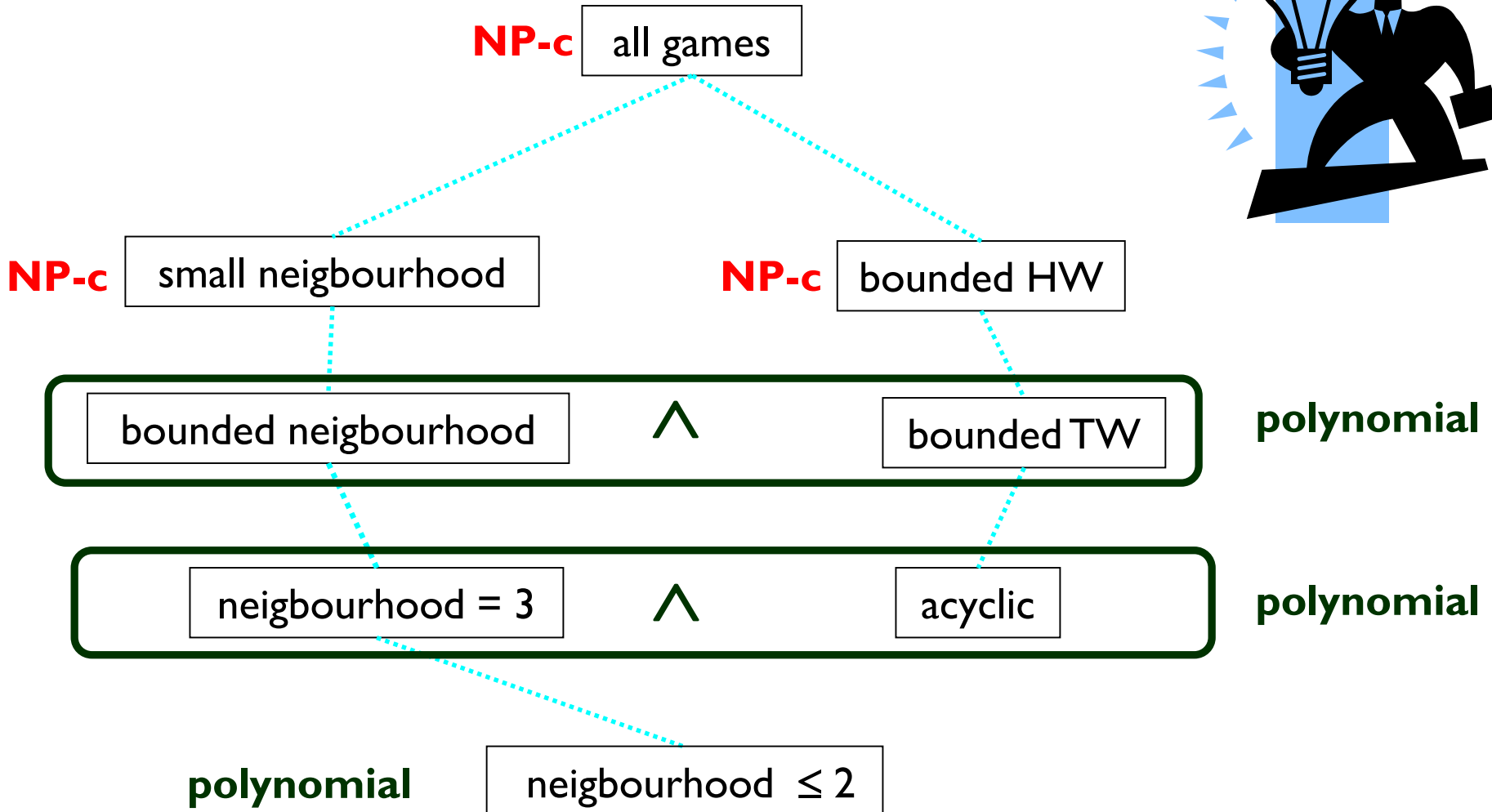
neighbourhood ≤ 2

Results [GG5'05]



EVEN BETTER NEWS:

CSP techniques



Results [GG5'05]



THE BEST NEWS:

CSP techniques



NP-c all games

small neighbourhood

\wedge

bounded HW

polynomial

bounded neighbourhood

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polynomial

neighbourhood = 3

\wedge

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polynomial

neighbourhood ≤ 2

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▶ Spinoff dell'Università della Calabria

- ▶ Ormai da 10 anni sul mercato
- ▶ E' una delle principali realtà imprenditoriali in Italia nell'ideazione e sviluppo di Business Simulation per la formazione manageriale ed il recruitment
- ▶ Collabora con: Scuole di Alta Formazione Manageriale, Grandi Aziende, Università, Associazioni di Categoria, Incubatori d'impresa



Business Games



I **Business Game** sono strumenti innovativi di simulazione manageriale che riproducono le dinamiche e le logiche di uno scenario “virtuale” competitivo.

Area	TEAM	Piattaforme Mobile
Leyo		
Mobile Developers	Esperienza Mobile Developers	
Business Developers	Esperienza Business Developers	
Creativi	Esperienza Creativi	
	Know how e Networking	
	Consulenze	

Funzionamento

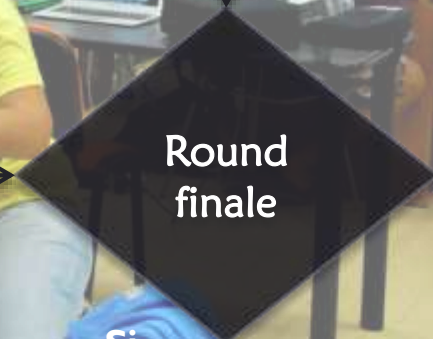


Composizione delle squadre

Presentazione dello scenario e delle regole del gioco

Avvio della simulazione e Debriefing sui risultati per ogni round di gioco

Inserimento di “imprevisti” per stimolare la reattività dei team in situazioni incerte



Debriefing sui risultati finali e Premiazione dei vincitori

BG e AI



Analista Artémat, presso il cliente



Modello di mercato, formalizzato nel linguaggio BGL



Compilatore del modello:

- Sistema sviluppato prototipalmente presso Artémat Lab
- Oggi, completamente ingegnerizzato



Applicativo web (autogenerato) che supporta il business game sul modello scelto



game !!!!



Supporto all'evento formativo mediante «facilitatori»




- Possibilità di introdurre aziende «virtuali» nell'evento, utili per:**
- Aumentare il realismo della simulazione, creando particolari condizioni di mercato
 - Aumentare la dimensione della simulazione, e rendere fruibile il sistema anche ad utenti singoli o classi di piccole dimensioni










Esempio Interfaccia






artemat  Team connesso: **Artemat** Budget residuo **6.720.218** Round: **6** **1** **2** 3 4 5 6 salva conferma esci

Dashboard


Leve di intervento

Marketing  12	Produzione  5	Acquisti  4
Distribuzione  3	Risorse Umane  9	Ricerca e Sviluppo  5
Amministrazione e Finanza  4	Tutte le leve  -	

Variabili

Stato aziendale  3	Concorrenti  1	Mercato  5
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Scenario



General Management
businessgame

Report Calcolatrice Note Info

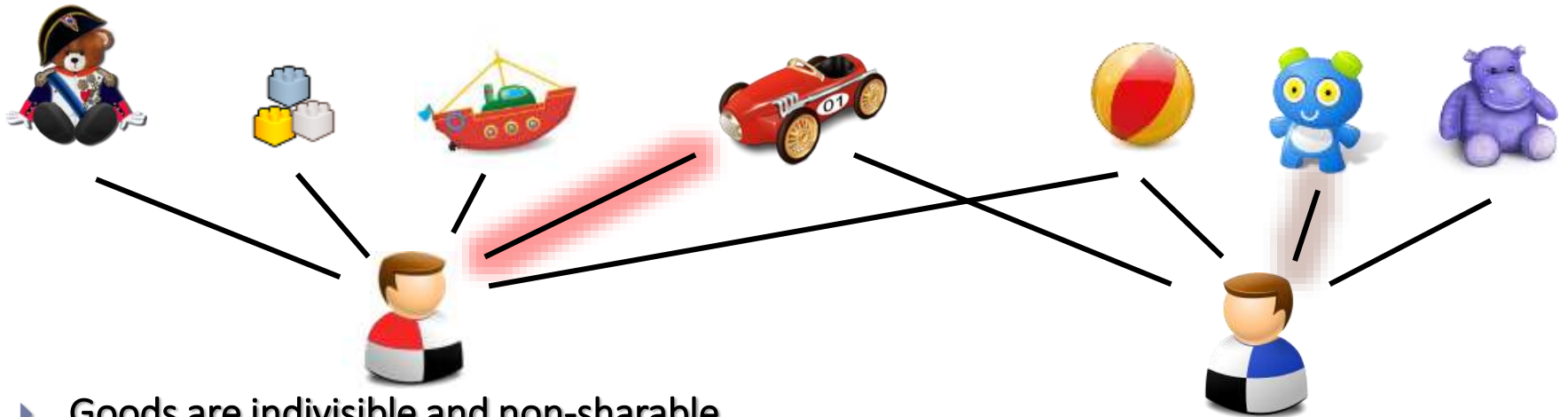
Catalogo dei Modelli



COOPERATIONAL GAMES



The Model



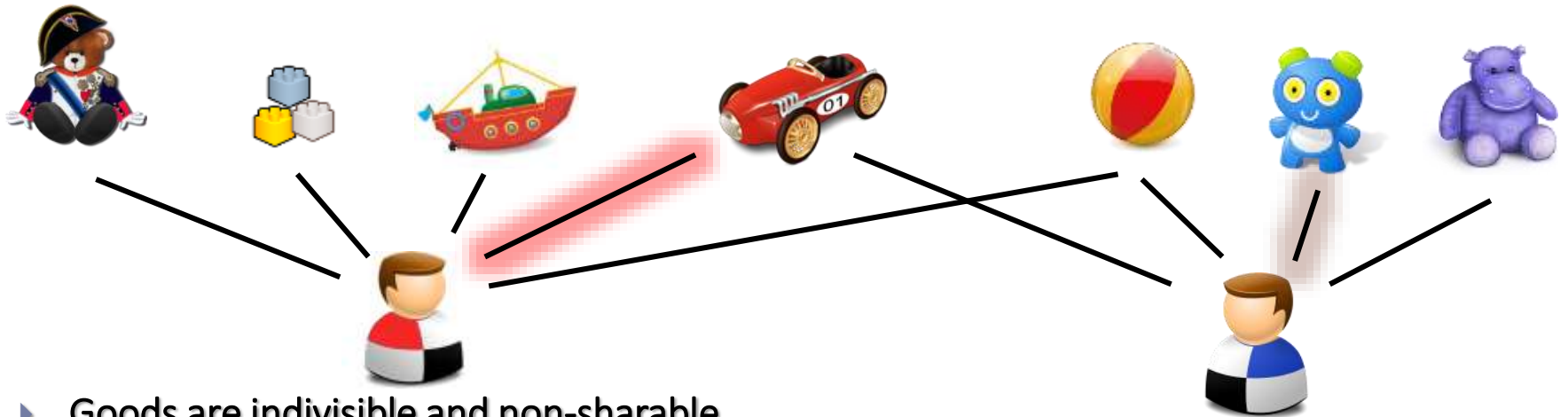
- ▶ Goods are indivisible and non-sharable
- ▶ Constraints on the max/min number of goods to be allocated to each agent
- ▶ Agent preferences: *Private* types VS *Declared* types



- Monetary compensation to induce truthfulness

see, e.g., [Shoham, Leyton-Brown; 2009]

The Model



- ▶ Goods are indivisible and non-sharable
- ▶ Constraints on the max/min number of goods to be allocated to each agent
- ▶ Agent preferences: *Private* types VS *Declared* types



- Monetary compensation to induce truthfulness
«budget balance»
 - The algebraic sum of the monetary transfers is zero
 - In particular, mechanisms cannot run into deficit

Goals of the Allocation



▶ «Efficiency»

- ▶ Maximize the social welfare

▶ «Fairness»

- ▶ For instance, it is desirable that *no agent envies* the allocation of any another agent, or that
- ▶ the selected outcome is *Pareto efficient*, i.e., there must be no different allocation such that every agent gets at least the same utility and one of them even improves.

see, e.g., [Brandt, Endriss; 2012]

Impossibility Results



Efficiency + Truthfulness + Budget Balance

[Green, Laffont; 1977]
[Hurwicz; 1975]



Fairness + Truthfulness + Budget Balance

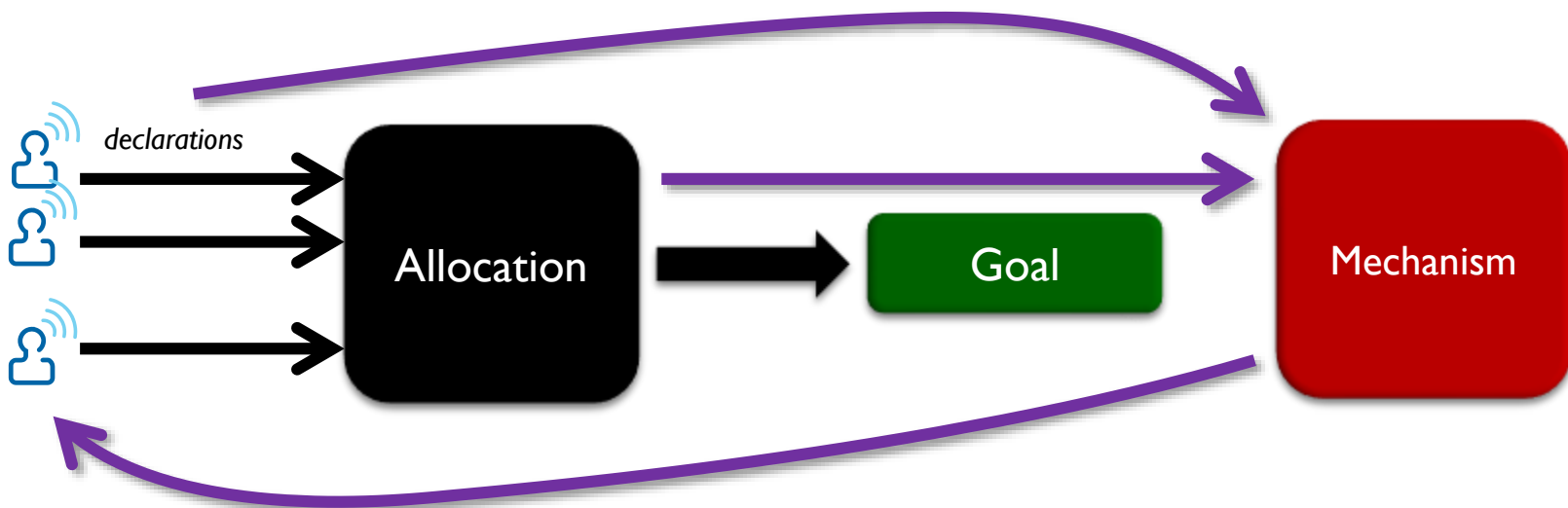
[Tadenuma, Thomson; 1995]
[Alcalde, Barberà; 1994]
[Andersson, Svensson, Ehlers; 2010]

Impossibility Results



☹️ Efficiency + Truthfulness + Budget Balance

☹️ Fairness + Truthfulness + Budget Balance



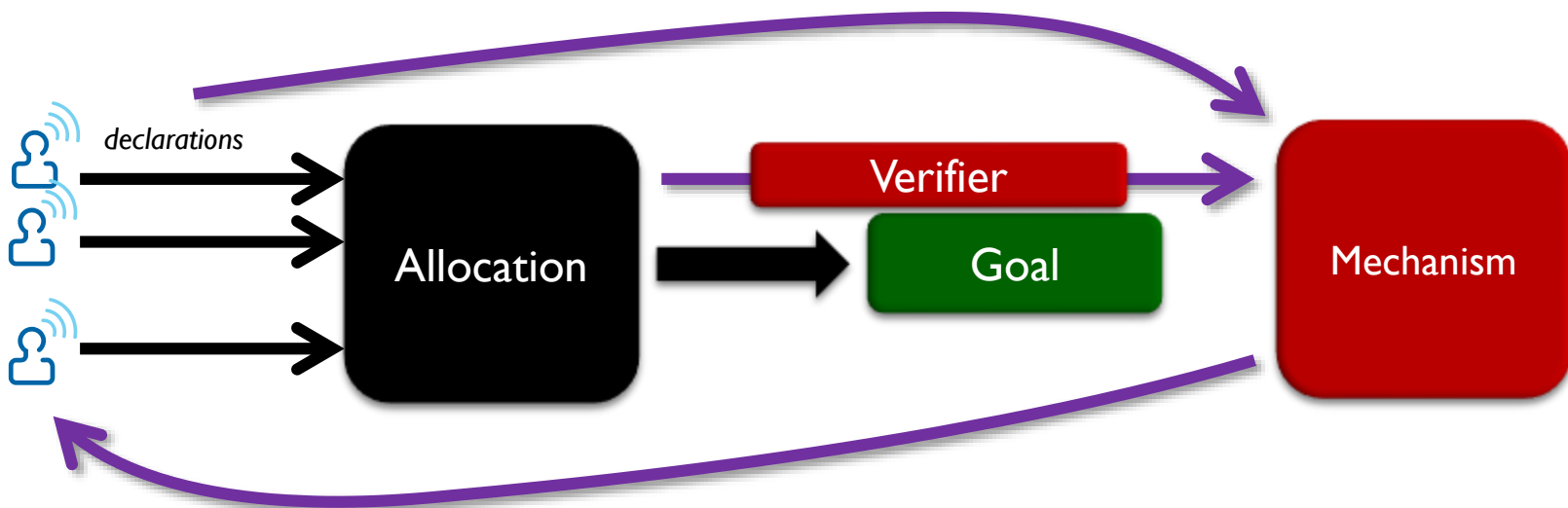
Impossibility Results



☹ Efficiency + Truthfulness + Budget Balance

☹ Fairness + Truthfulness + Budget Balance

▶ Verification on «selected» declarations



Approaches to Verification



(1) Partial Verification

[Green, Laffont; 1986]

[Nisan, Ronen; 2001]

(2) Probabilistic Verification

*Punishments are used
to enforce truthfulness*

Approaches to Verification



(1) Partial Verification

[Auletta, De Prisco, Ferrante, Krysta, Parlato, Penna, Persiano, Sorrentino, Ventre]

(2) Probabilistic Verification

Punishments are used to enforce truthfulness

Approaches to Verification



(1) Partial Verification

[Auletta, De Prisco, Ferrante, Krysta, Parlato, Penna, Persiano, Sorrentino, Ventre]

(2) Probabilistic Verification

[Caragiannis, Elkind, Szegedy, Yu; 2012]

*Punishments are used
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Approaches to Verification



(1) Partial Verification

(2) Probabilistic Verification



*Punishments are used
to enforce truthfulness*

(3) Full Verification



No punishments!

VQR 2004-2010



- ▶ VQR 2004-2010: ANVUR should evaluate the quality of research of all Italian research structures
- ▶ Funds for the structures in the next years depend on the outcome of this evaluation
- ▶ Substructures will be also evaluated (e.g. university departments)

ANVUR Evaluation



ANVUR Criteria



ANVUR Evaluation



ANVUR Criteria



Self-evaluations



$score_r(p)$, for each

$$\left\{ \begin{array}{l} r \in \mathcal{R} \\ p \in products(r) \end{array} \right.$$

ANVUR Evaluation



ANVUR Criteria



Self-evaluations

$score_r(p)$



Structures are in charge of selecting the products to submit

ANVUR Evaluation



ANVUR Criteria



Self-evaluations



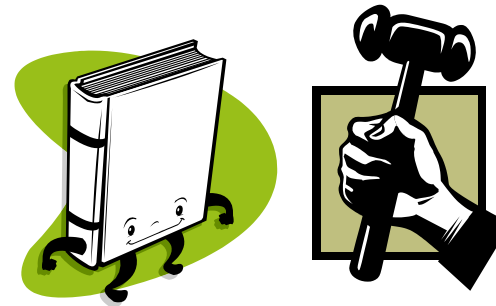
$score_r(p)$

ANVUR Evaluation



$score_{VQR}(p)$

Selected publications



ANVUR Evaluation



ANVUR Criteria



Self-evaluations



$score_r(p)$



Selected publications



$score_{VQR}(p)$



Evaluation



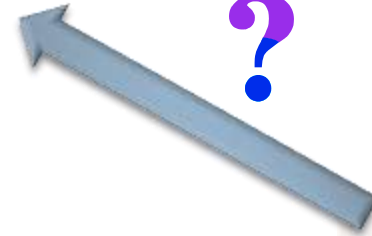
ANVUR Evaluation



ANVUR Criteria



Division Rules



Self-evaluations



$score_r(p)$



Selected publications



$score_{VQR}(p)$



Evaluation



ANVUR Evaluation



ANVUR Criteria



Division Rules



Self-evaluations



$score_r(p)$

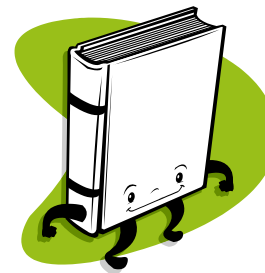


Selected publications



$score_{VQR}(p)$

Evaluation



$$\text{proj}_r(\psi^*) = \sum_{p \in \psi^*(r)} \text{score}_{VQR}(p)$$

The Mechanism [GS'19]



Input: An allocation π for $\langle \mathcal{A}, G, \omega \rangle$, and a vector $\mathbf{w} \in \mathbf{D}$;

Assumption: A verifier \mathbf{v} is available. Let $\mathbf{v}(\pi) = (v_1, \dots, v_n)$;

1. Let \mathcal{C} denote the set of all possible subsets of \mathcal{A} ;
2. For each set $\mathcal{C} \in \mathcal{C}$,
3. | Compute an optimal allocation $\pi_{\mathcal{C}}$ for $\langle \mathcal{C}, \text{img}(\pi), \omega \rangle$ w.r.t. \mathbf{w} ;
4. For each agent $i \in \mathcal{A}$,
5. | For each set $\mathcal{C} \in \mathcal{C}$,
6. | | Let $\Delta_{\mathcal{C},i}^1(\pi, \mathbf{w}) := \text{val}(\pi_{\mathcal{C}}, (v_i, \mathbf{w}_{-i}))$; $(=v_i(\pi_{\mathcal{C}}) + \sum_{j \in \mathcal{C} \setminus \{i\}} w_j(\pi_{\mathcal{C}}))$;
7. | | Let $\Delta_{\mathcal{C},i}^2(\pi, \mathbf{w}) := \text{val}(\pi_{\mathcal{C} \setminus \{i\}}, \mathbf{w})$; $(= \sum_{j \in \mathcal{C} \setminus \{i\}} w_j(\pi_{\mathcal{C} \setminus \{i\}}))$;
8. | Let $\xi_i(\pi, \mathbf{w}) := \sum_{\mathcal{C} \in \mathcal{C}} \frac{(|\mathcal{A}| - |\mathcal{C}|)! (|\mathcal{C}| - 1)!}{|\mathcal{A}|!} (\Delta_{\mathcal{C},i}^1(\pi, \mathbf{w}) - \Delta_{\mathcal{C},i}^2(\pi, \mathbf{w}))$;
9. | Define $p_i^{\xi}(\pi, \mathbf{w}) := \xi_i(\pi, \mathbf{w}) - v_i(\pi)$;

The Mechanism [GS'19]



Input: An allocation π for $\langle \mathcal{A}, G, \omega \rangle$, and a vector $\mathbf{w} \in \mathbf{D}$;

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The Mechanism [GS'19]



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7. | | Let $\Delta_{\mathcal{C},i}^2(\pi, \mathbf{w}) := \text{val}(\pi_{\mathcal{C} \setminus \{i\}}, \mathbf{w})$; $(= \sum_{j \in \mathcal{C} \setminus \{i\}} w_j(\pi_{\mathcal{C} \setminus \{i\}}))$;
8. | Let $\xi_i(\pi, \mathbf{w}) := \sum_{\mathcal{C} \in \mathbb{C}} \frac{(|\mathcal{A}| - |\mathcal{C}|)! (|\mathcal{C}| - 1)!}{|\mathcal{A}|!} (\Delta_{\mathcal{C},i}^1(\pi, \mathbf{w}) - \Delta_{\mathcal{C},i}^2(\pi, \mathbf{w}))$;
9. | Define $p_i^{\xi}(\pi, \mathbf{w}) := \xi_i(\pi, \mathbf{w}) - v_i(\pi)$;



Allocated goods are considered only



In fact, allocated goods are the only ones that we verify

The Mechanism [GS'19]



Input: An allocation π for $\langle \mathcal{A}, G, \omega \rangle$, and a vector $\mathbf{w} \in \mathbf{D}$;

Assumption: A verifier \mathbf{v} is available. Let $\mathbf{v}(\pi) = (v_1, \dots, v_n)$;

1. Let \mathcal{C} denote the set of all possible subsets of \mathcal{A} ;
2. For each set $\mathcal{C} \in \mathcal{C}$,
3. | Compute an optimal allocation $\pi_{\mathcal{C}}$ for $\langle \mathcal{C}, \text{img}(\pi), \omega \rangle$ w.r.t. \mathbf{w} ;
4. For each agent $i \in \mathcal{A}$,
5. | For each set $\mathcal{C} \in \mathcal{C}$,
6. | | Let $\Delta_{\mathcal{C},i}^1(\pi, \mathbf{w}) := \text{val}(\pi_{\mathcal{C}}, (v_i, \mathbf{w}_{-i}))$; $(=v_i(\pi_{\mathcal{C}}) + \sum_{j \in \mathcal{C} \setminus \{i\}} w_j(\pi_{\mathcal{C}}))$;
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9. | Define $p_i^{\xi}(\pi, \mathbf{w}) := \xi_i(\pi, \mathbf{w}) - v_i(\pi)$;

«Bonus and Compensation»,
by Nisan and Ronen (2001)

The Mechanism [GS'19]



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Assumption: A verifier \mathbf{v} is available. Let $\mathbf{v}(\pi) = (v_1, \dots, v_n)$;

1. Let \mathbb{C} denote the set of all possible subsets of \mathcal{A} ;
2. For each set $C \in \mathbb{C}$,
3. | Compute an optimal allocation π_C for $\langle C, \text{img}(\pi), \omega \rangle$ w.r.t. \mathbf{w} ;
4. For each agent $i \in \mathcal{A}$,
5. | For each set $C \in \mathbb{C}$,
6. | | Let $\Delta_{C,i}^1(\pi, \mathbf{w}) := \text{val}(\pi_C, (v_i, \mathbf{w}_{-i}))$; $(=v_i(\pi_C) + \sum_{j \in C \setminus \{i\}} w_j(\pi_C))$;
7. | | Let $\Delta_{C,i}^2(\pi, \mathbf{w}) := \text{val}(\pi_{C \setminus \{i\}}, \mathbf{w})$; $(=\sum_{j \in C \setminus \{i\}} w_j(\pi_{C \setminus \{i\}}))$;
8. | Let $\xi_i(\pi, \mathbf{w}) := \sum_{C \in \mathbb{C}} \frac{(|\mathcal{A}| - |C|)! (|C| - 1)!}{|\mathcal{A}|!} (\Delta_{C,i}^1(\pi, \mathbf{w}) - \Delta_{C,i}^2(\pi, \mathbf{w}))$;
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Allocated goods are considered only

«Bonus and Compensation»,
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No punishments!

The Mechanism [GS'19]



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9. | Define $p_i^{\xi}(\pi, \mathbf{w}) := \xi_i(\pi, \mathbf{w}) - v_i(\pi)$;

«Bonus and Compensation»,
by Nisan and Ronen (2001)

❖ Truth-telling is a dominant strategy for each agent

The Mechanism [GS'19]



Input: An allocation π for $\langle \mathcal{A}, G, \omega \rangle$, and a vector $\mathbf{w} \in \mathbf{D}$;

Assumption: A verifier \mathbf{v} is available. Let $\mathbf{v}(\pi) = (v_1, \dots, v_n)$;

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9. | Define $p_i^c(\pi, \mathbf{w}) := \xi_i(\pi, \mathbf{w}) - v_i(\pi)$;

Allocated goods are considered only

«Bonus and Compensation»,
by Nisan and Ronen (2001)

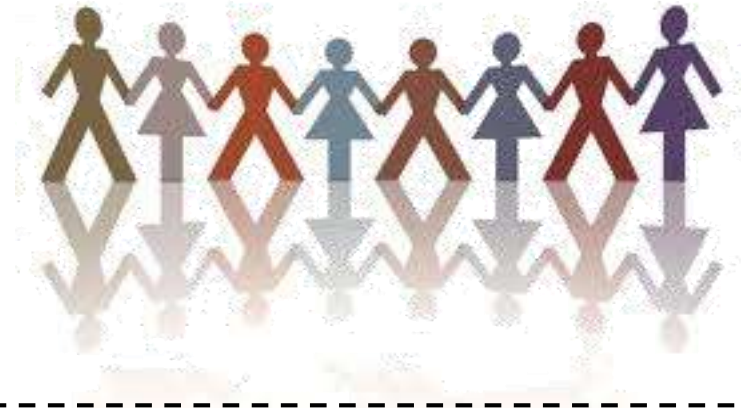
❖ Truth-telling is a dominant strategy for each agent

Coalitional Games



- ▶ Players form *coalitions*
- ▶ Each coalition is associated with a *worth*
- ▶ A *total worth* has to be distributed

$$\mathcal{G} = \langle N, \varphi \rangle, \varphi: 2^N \mapsto \mathbb{R}$$



-
- **Solution Concepts** characterize outcomes in terms of
 - Fairness
 - Stability

Shapley Value



$$\phi_i(\mathcal{G}) = \sum_{C \subseteq N} \frac{(|N| - |C|)! (|C| - 1)!}{|N|!} (\varphi(C) - \varphi(C \setminus \{i\}))$$

-
- **Solution Concepts** characterize outcomes in terms of
 - Fairness
 - Stability

The Mechanism [GS'19]



$$\mathcal{G} = \langle N, \varphi \rangle, \varphi: 2^N \mapsto \mathbb{R}$$

$\varphi(C)$ is the *contribution* of the coalition **w.r.t.**

selected products
and
verified values

The Mechanism [GS'19]



$$\mathcal{G} = \langle N, \varphi \rangle, \varphi: 2^N \mapsto \mathbb{R}$$

$\varphi(C)$ is the *contribution* of the coalition **w.r.t.**

{ selected products
and
verified values



**Best possible allocation,
assuming that agents in **C** are the only ones in the game**

The Mechanism [GS'19]



$$\mathcal{G} = \langle N, \varphi \rangle, \varphi: 2^N \mapsto \mathbb{R}$$

$\varphi(C)$ is the *contribution* of the coalition **w.r.t.**

{ **selected products**
and
verified values



Each researcher gets the Shapley value $\phi_i(\mathcal{G})$

The Mechanism [GS'19]



$$\mathcal{G} = \langle N, \varphi \rangle, \varphi: 2^N \mapsto \mathbb{R}$$

▶ $\varphi(C)$ is the *contribution* of the coalition **w.r.t.**

{ selected products
and
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Each researcher gets the Shapley value

$$\phi_i(\mathcal{G})$$

Properties

- ▶ The resulting mechanism is «efficient», «fair» and «budget balanced»
- ▶ Essentially, it is the **only** possible mechanism enjoying these properties!



GRAPHICS